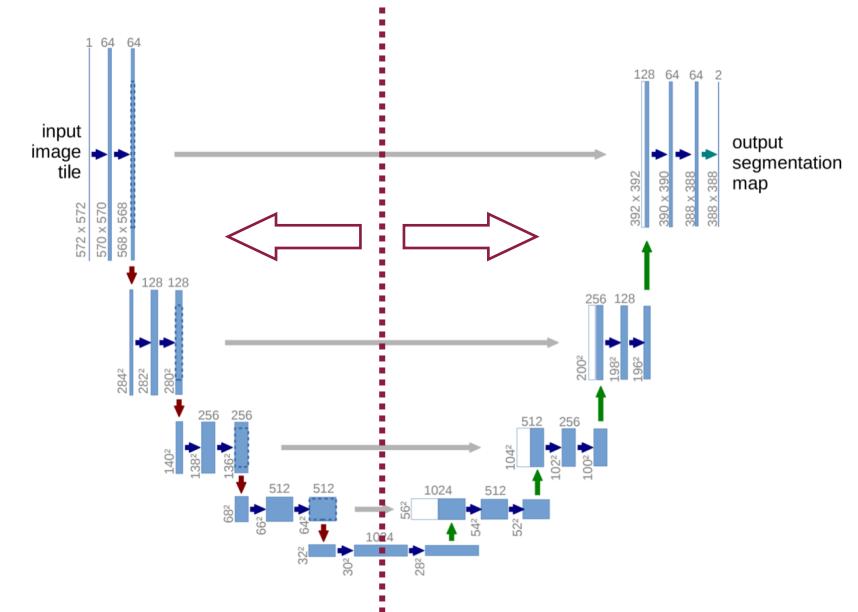
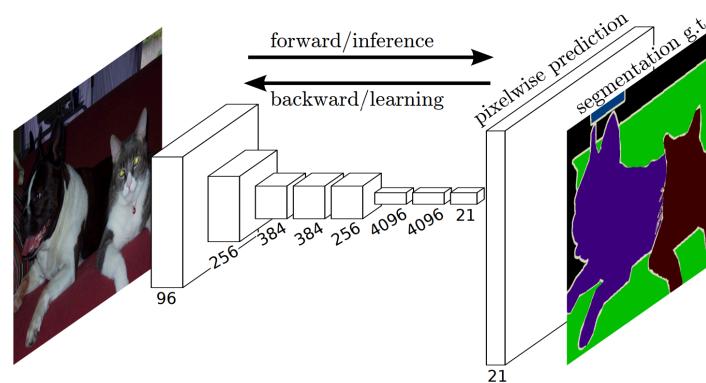


UNet++: A Nested U-Net Architecture for Medical Image Segmentation

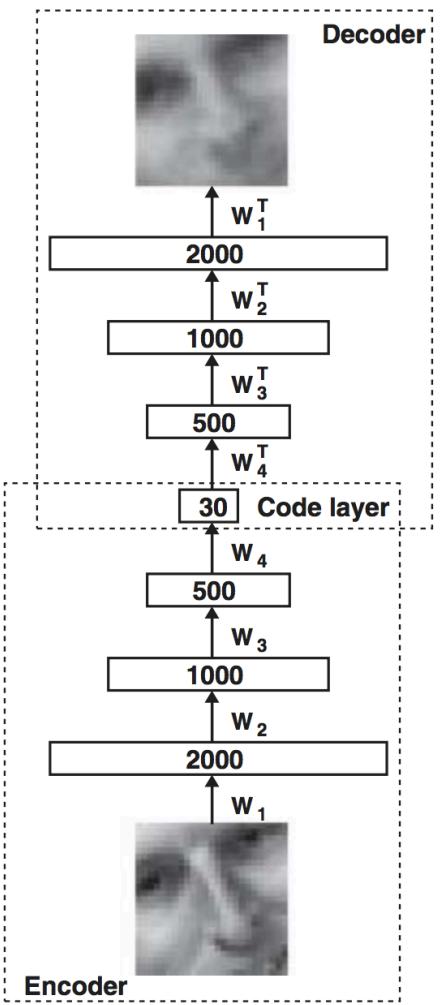
Zongwei Zhou, Md Mahfuzur Rahman Siddiquee, Nima Tajbakhsh, and Jianming Liang

Arizona State University

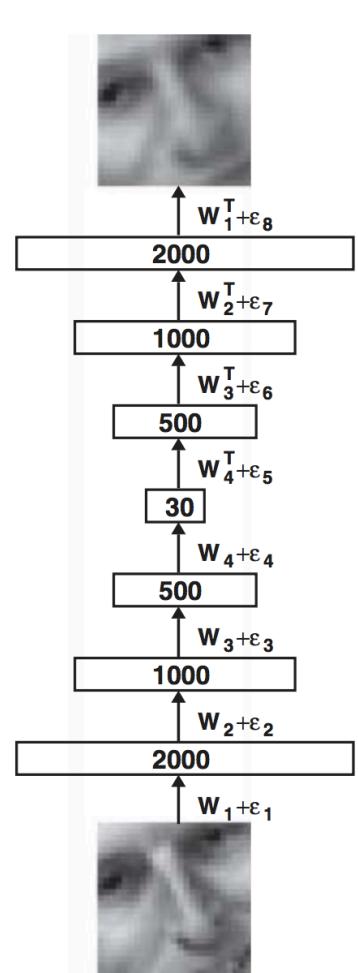


(Ronneberger, 2015)

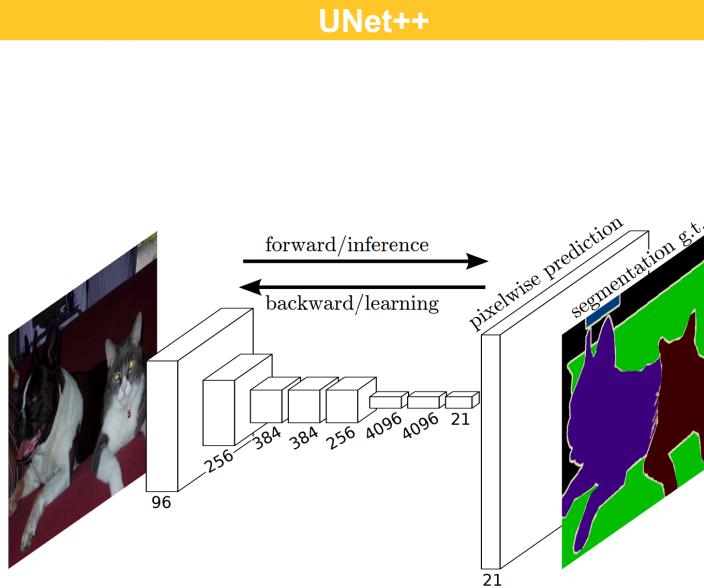
(Long, 2015)



Unrolling



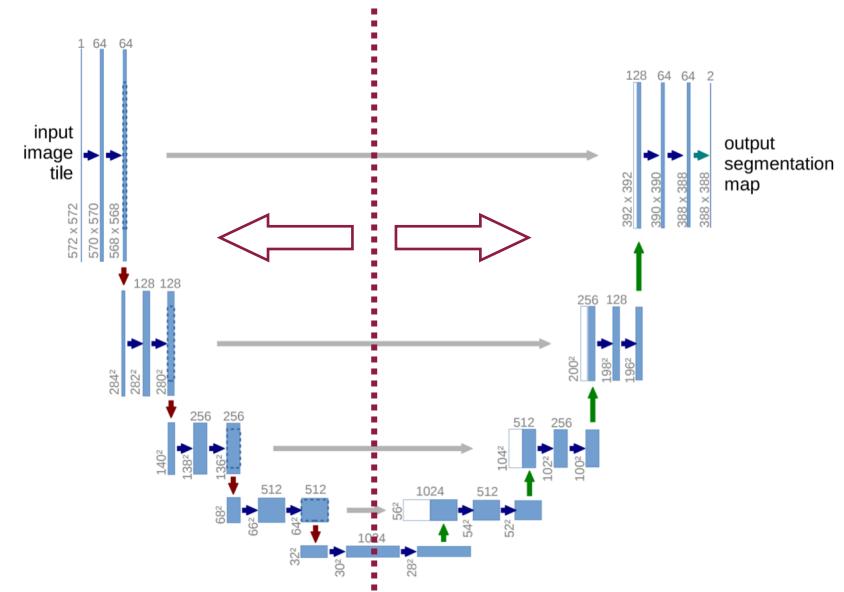
Fine-tuning

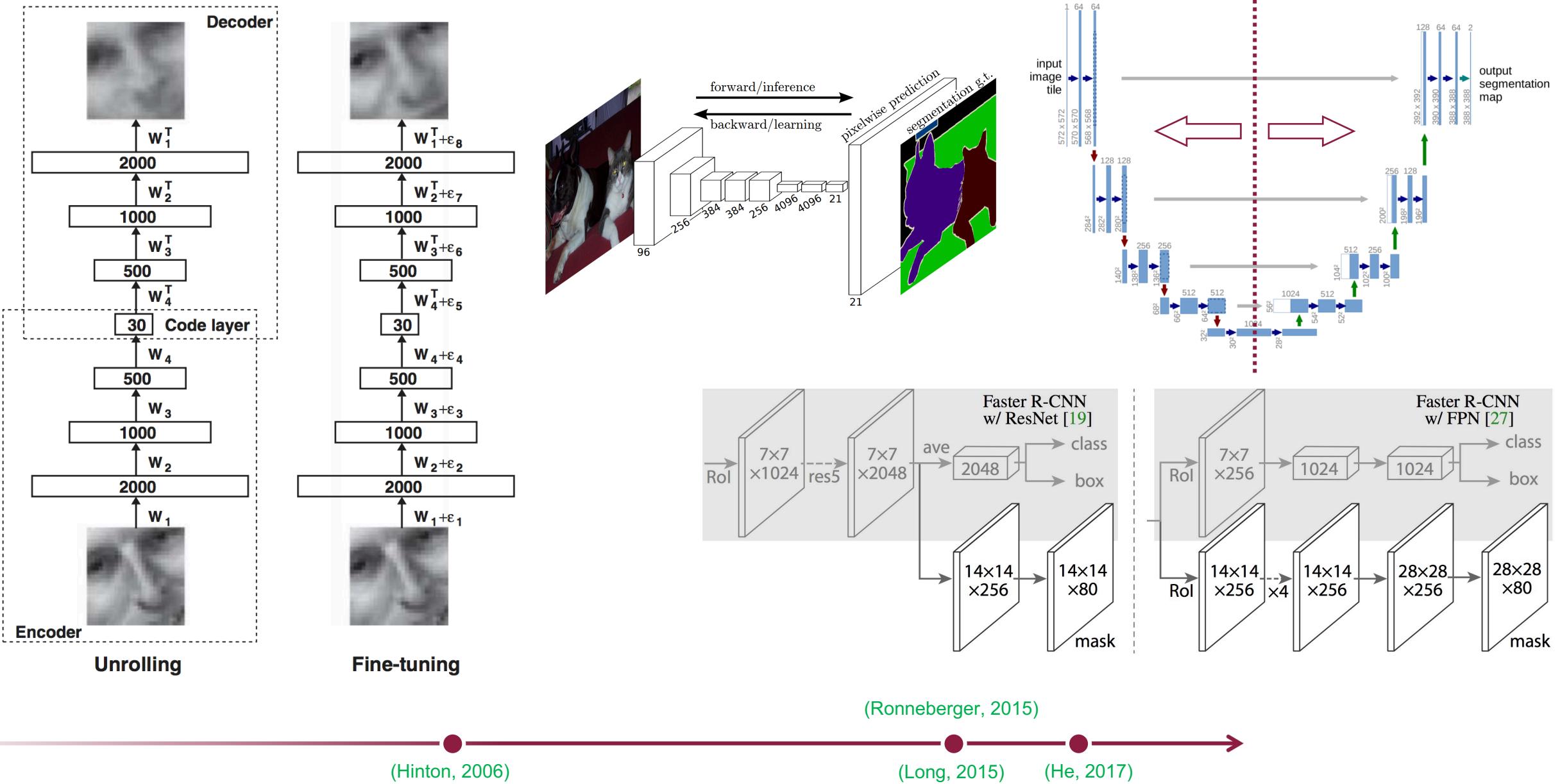


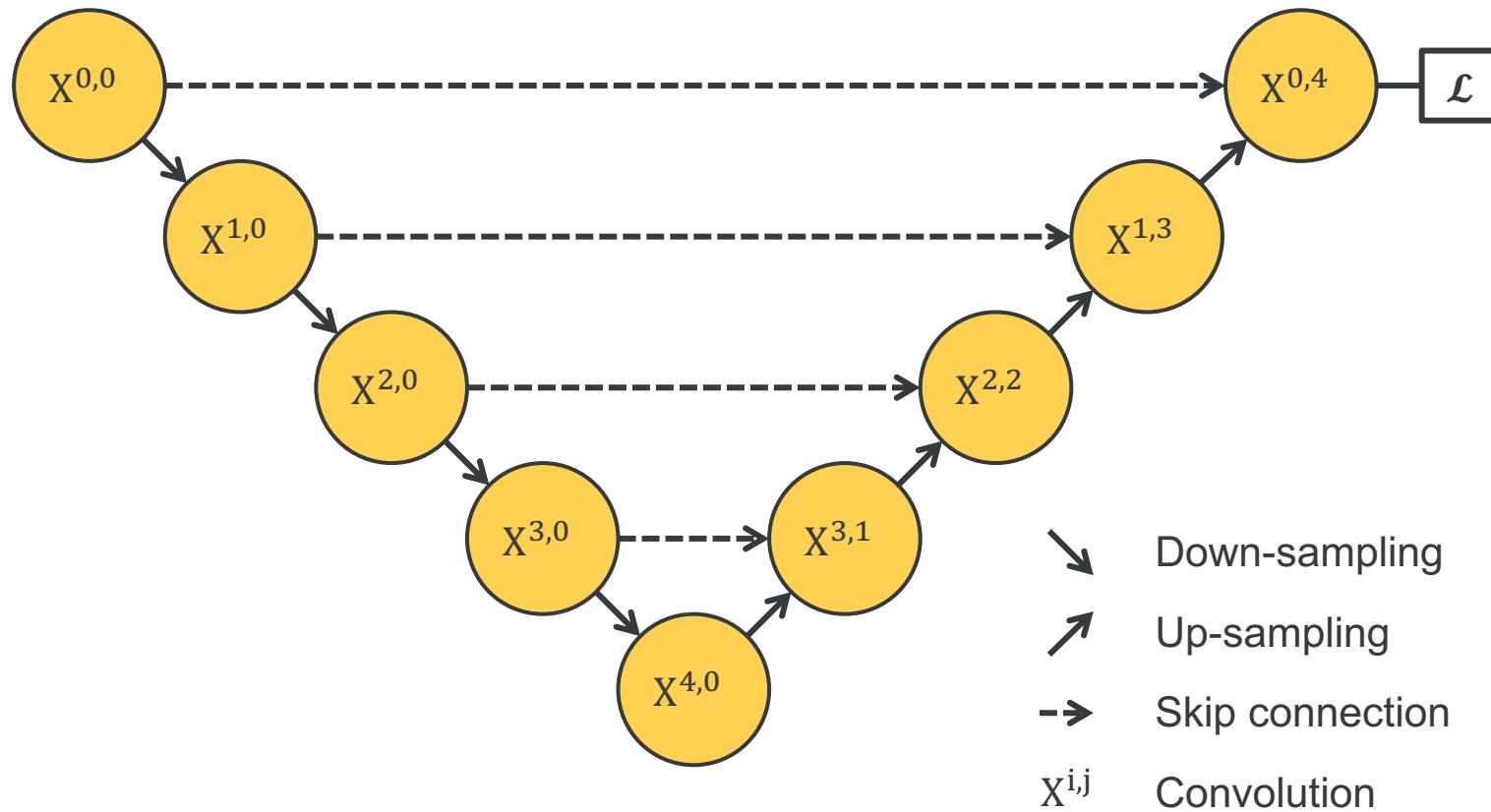
(Ronneberger, 2015)

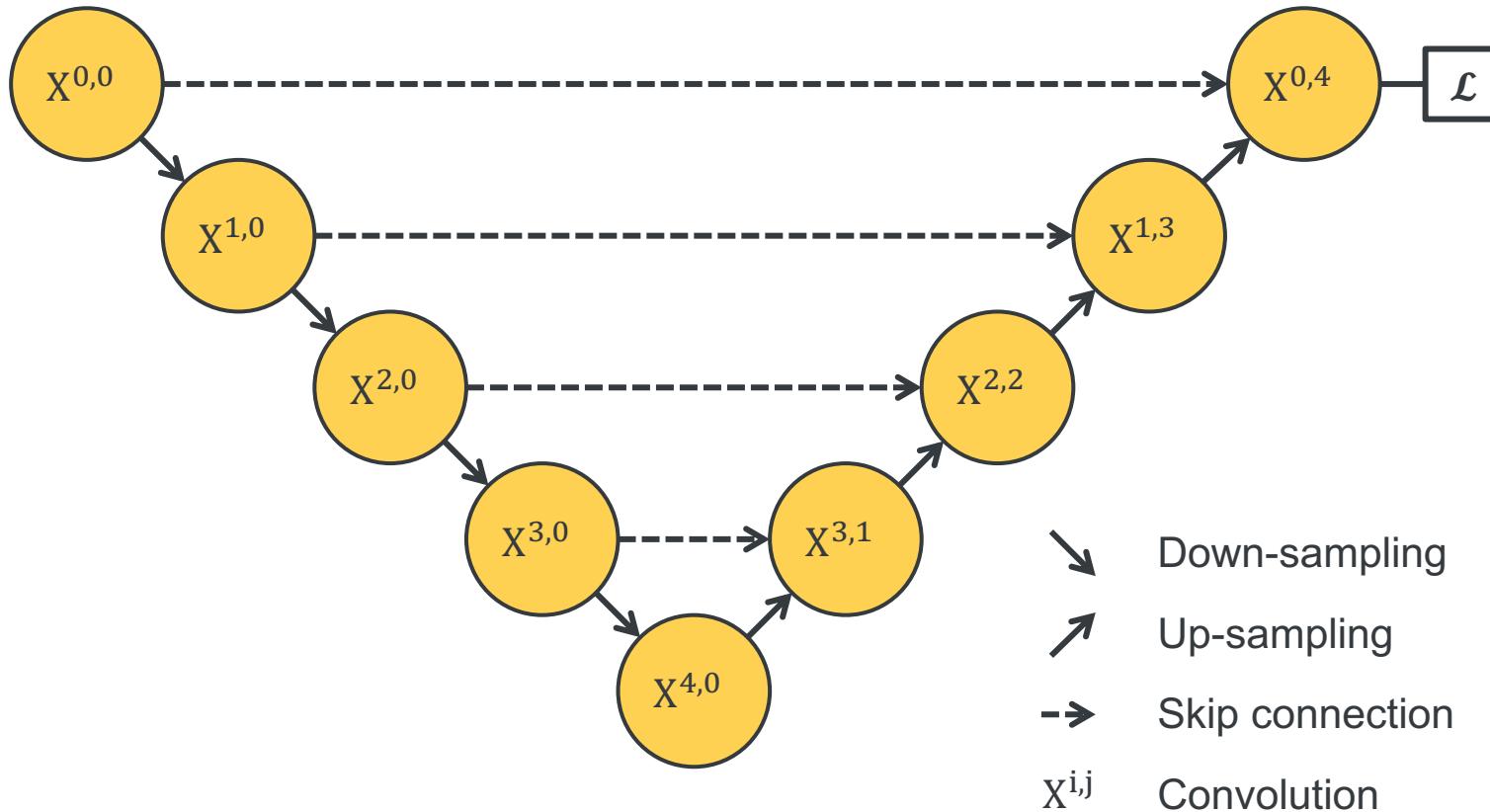
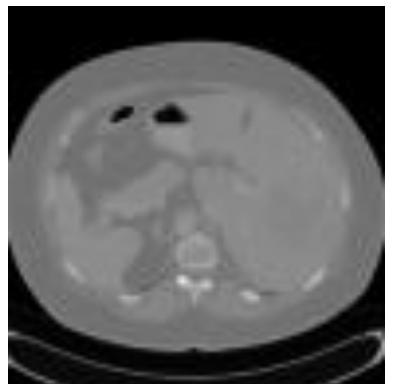
(Hinton, 2006)

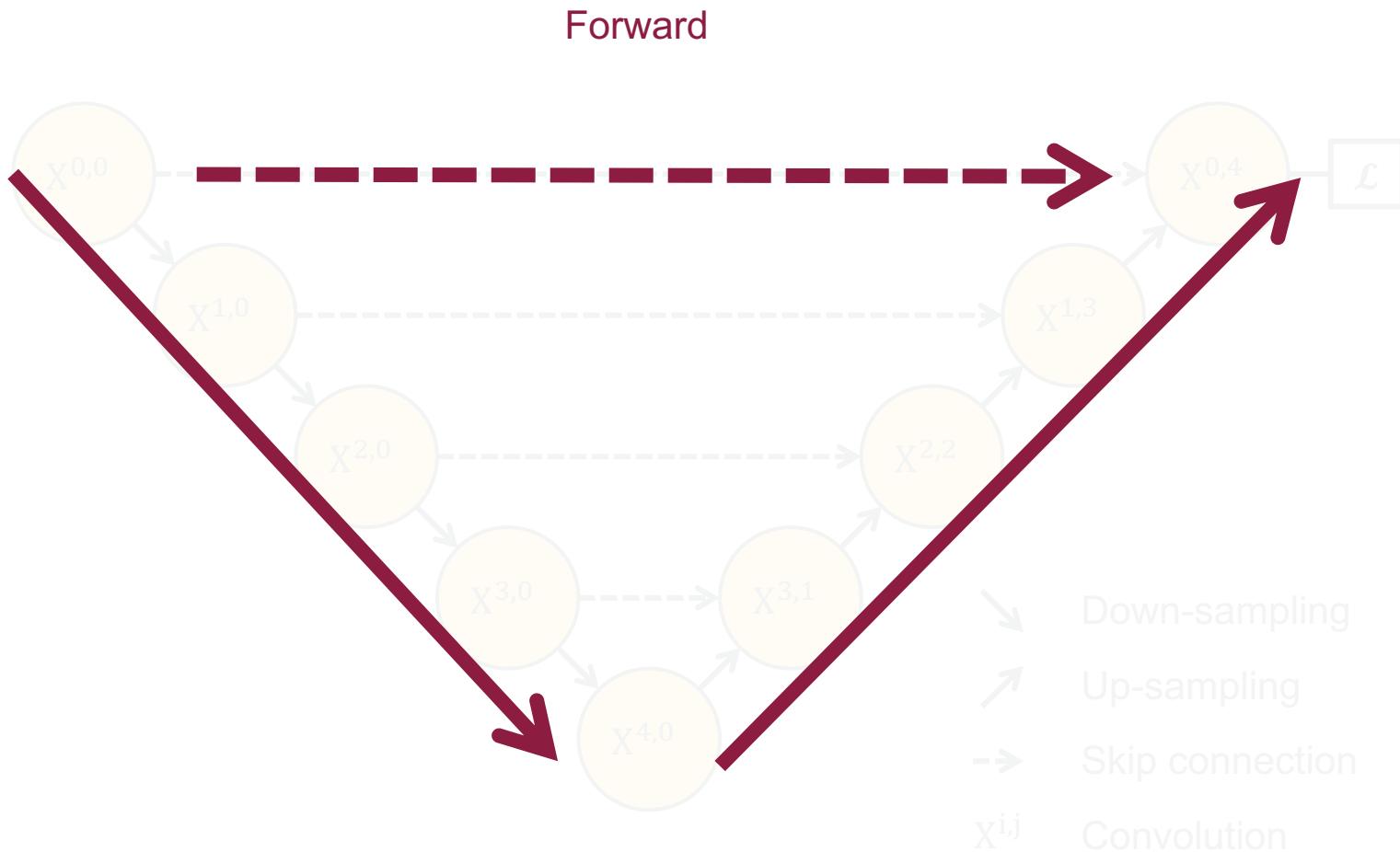
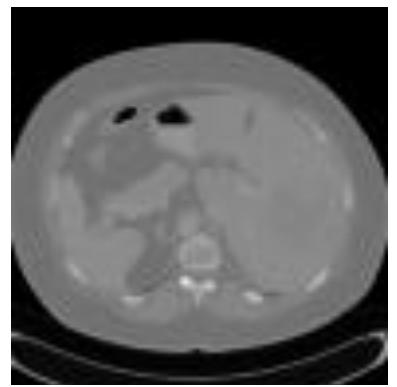
(Long, 2015)

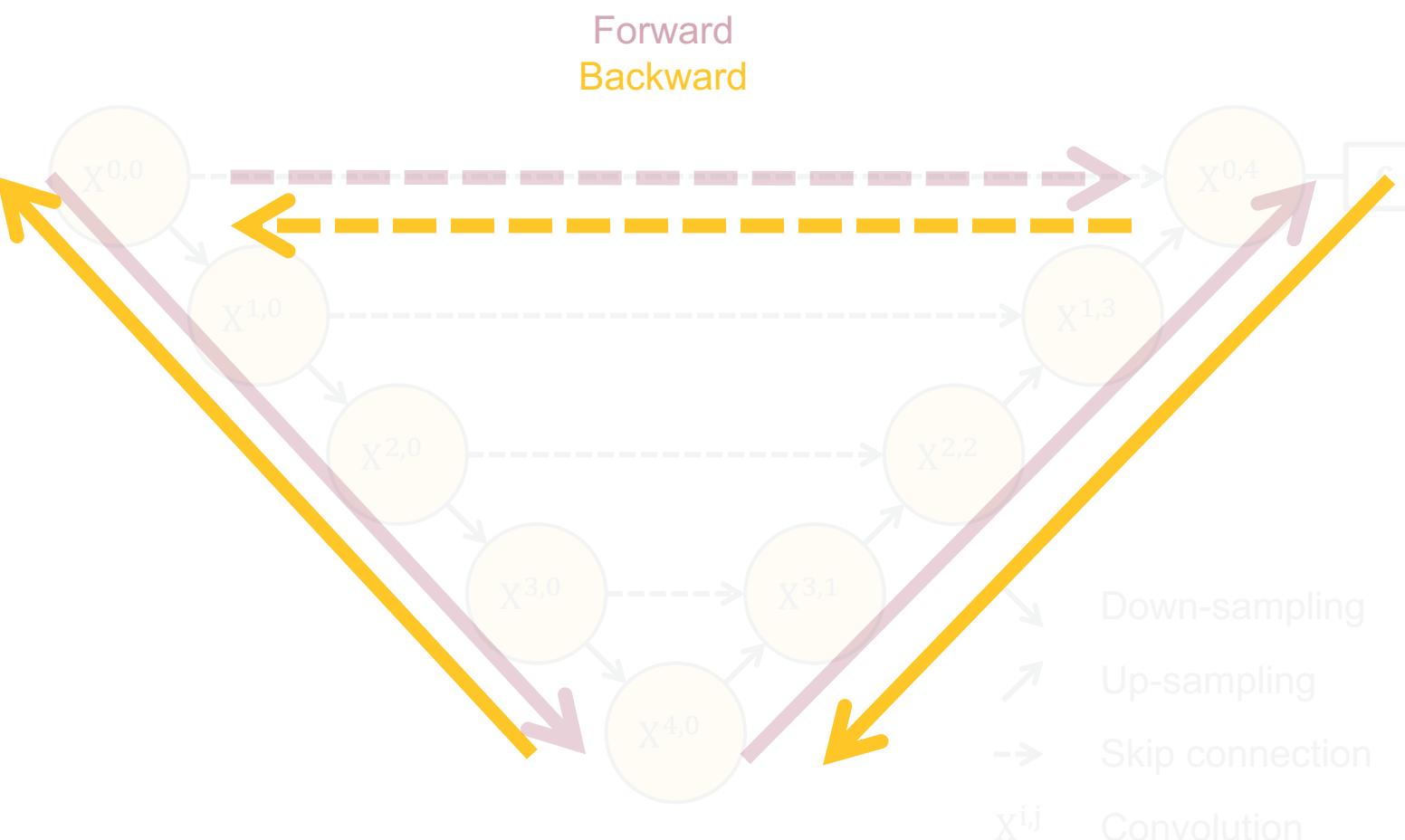
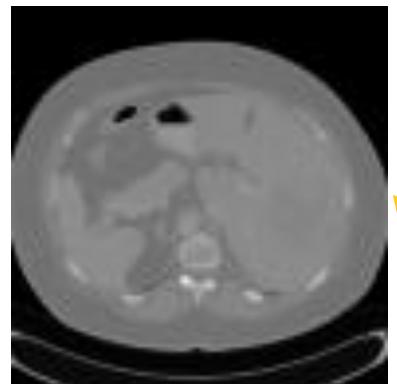


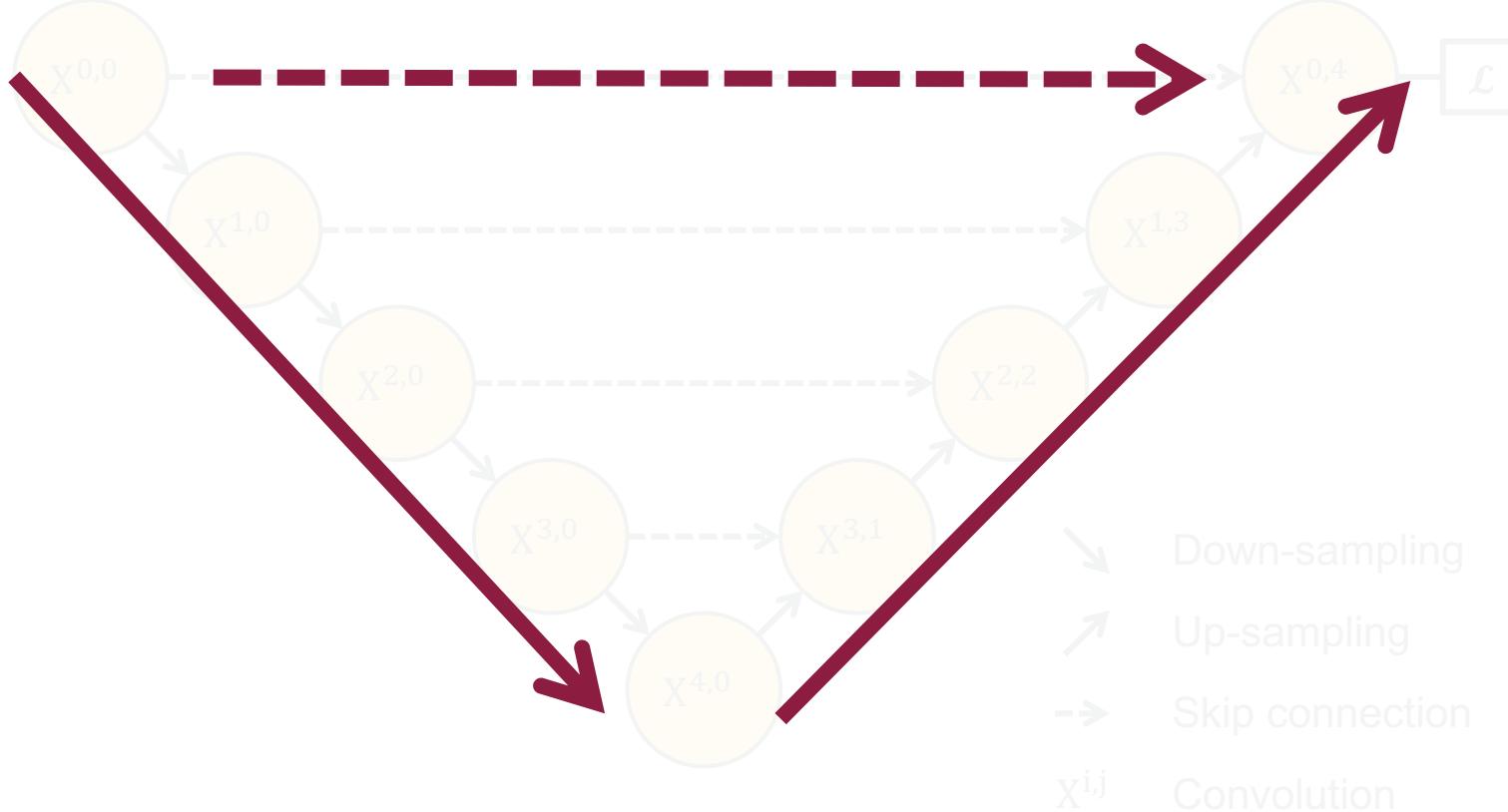
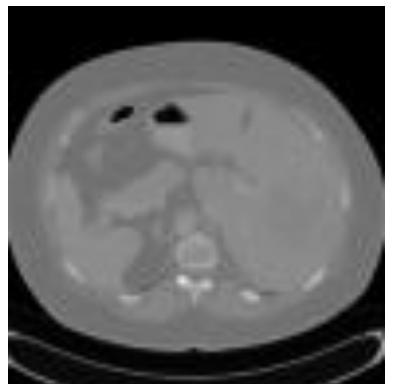


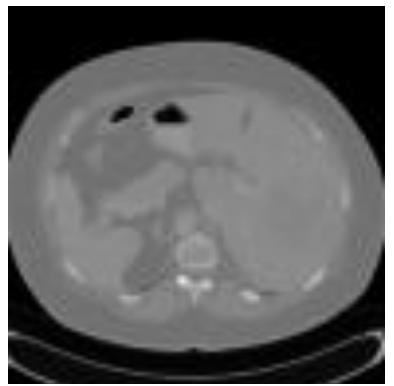




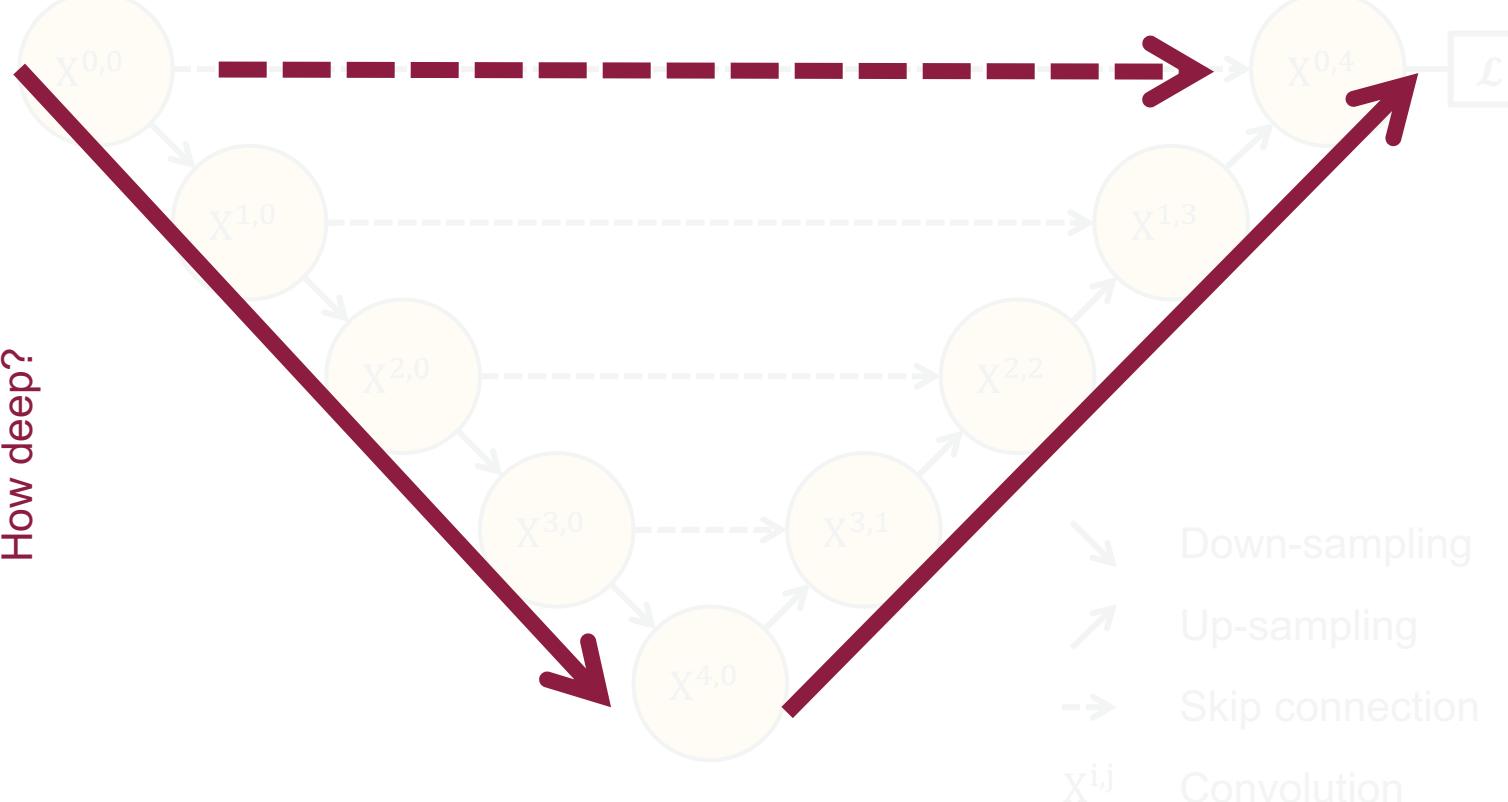


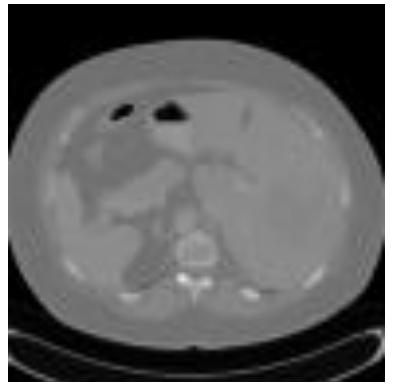




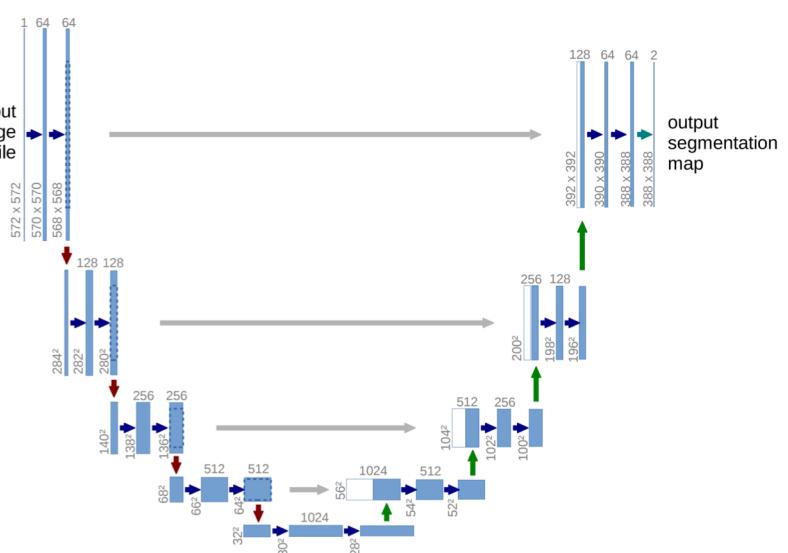
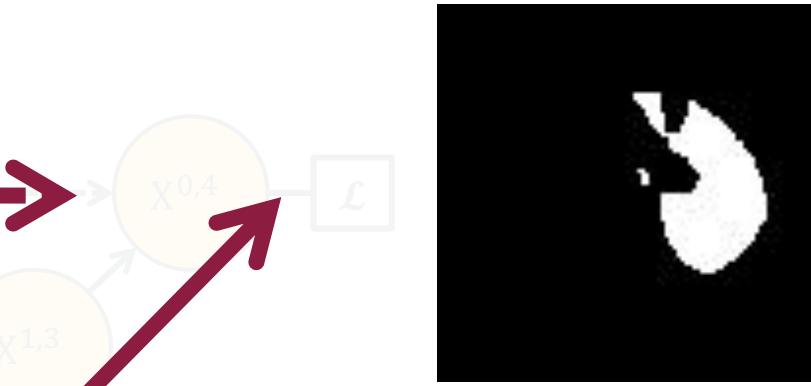
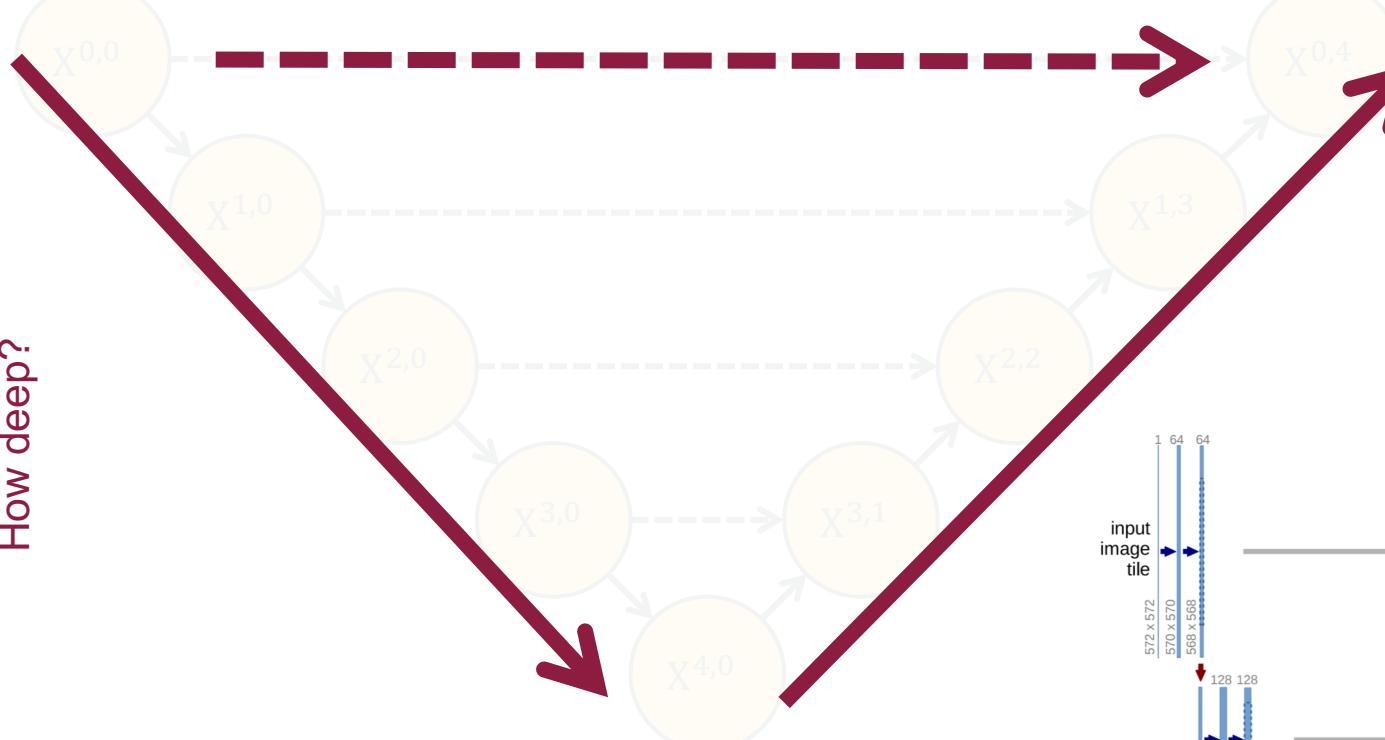


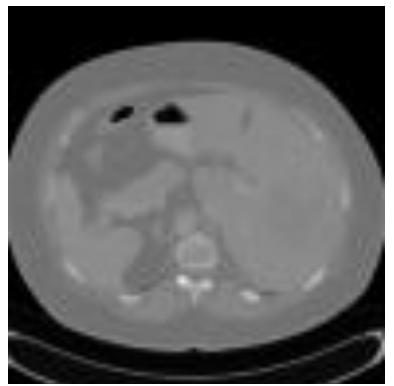
How deep?



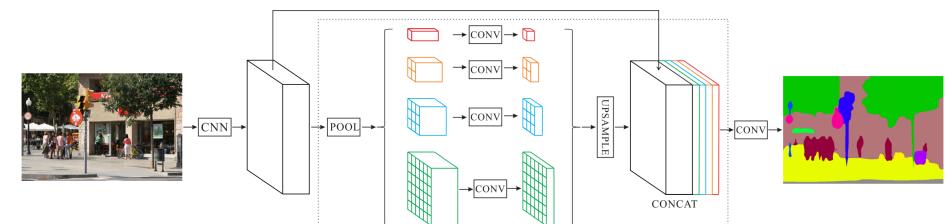
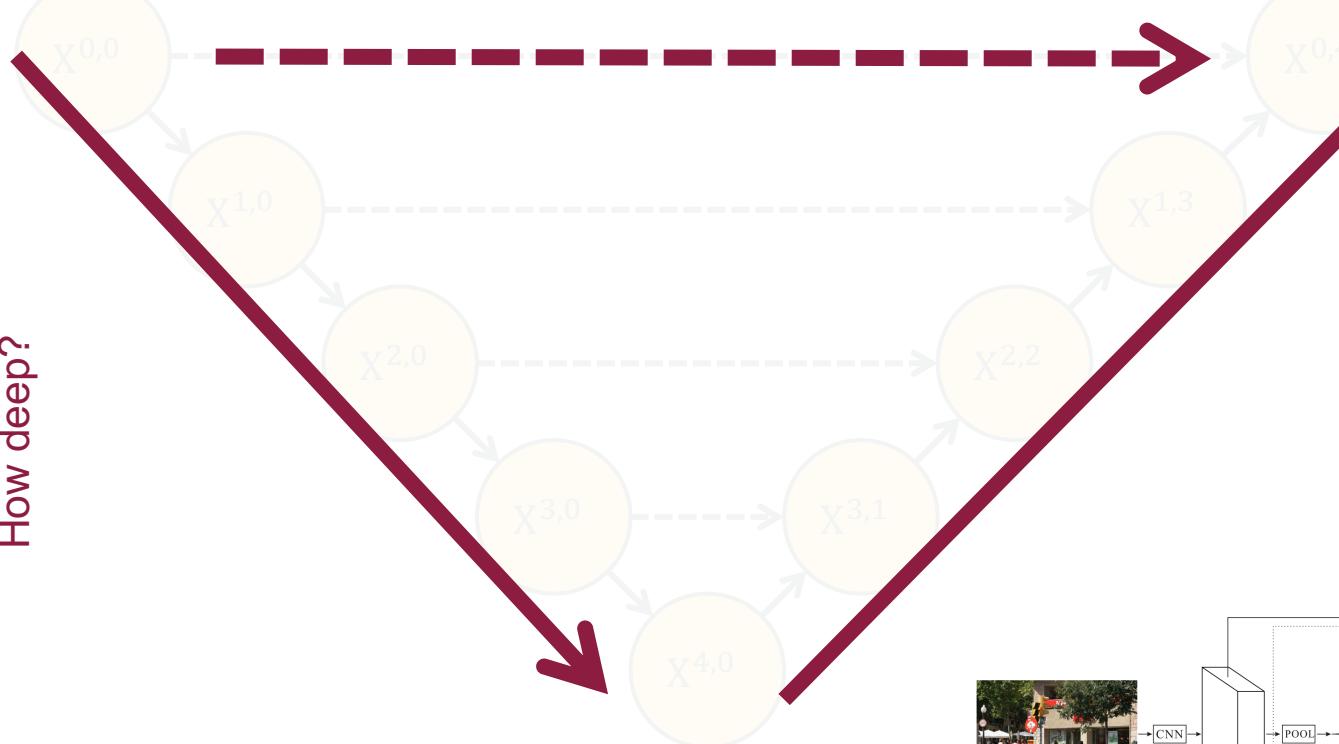


How deep?



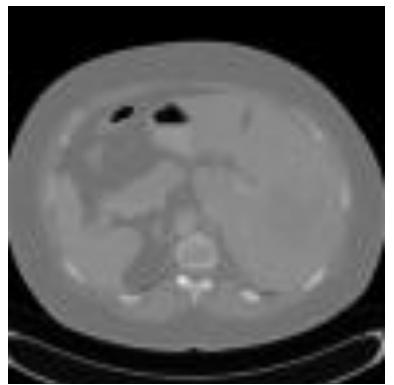


How deep?

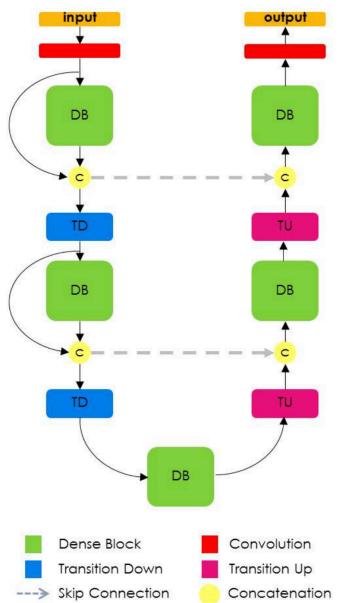
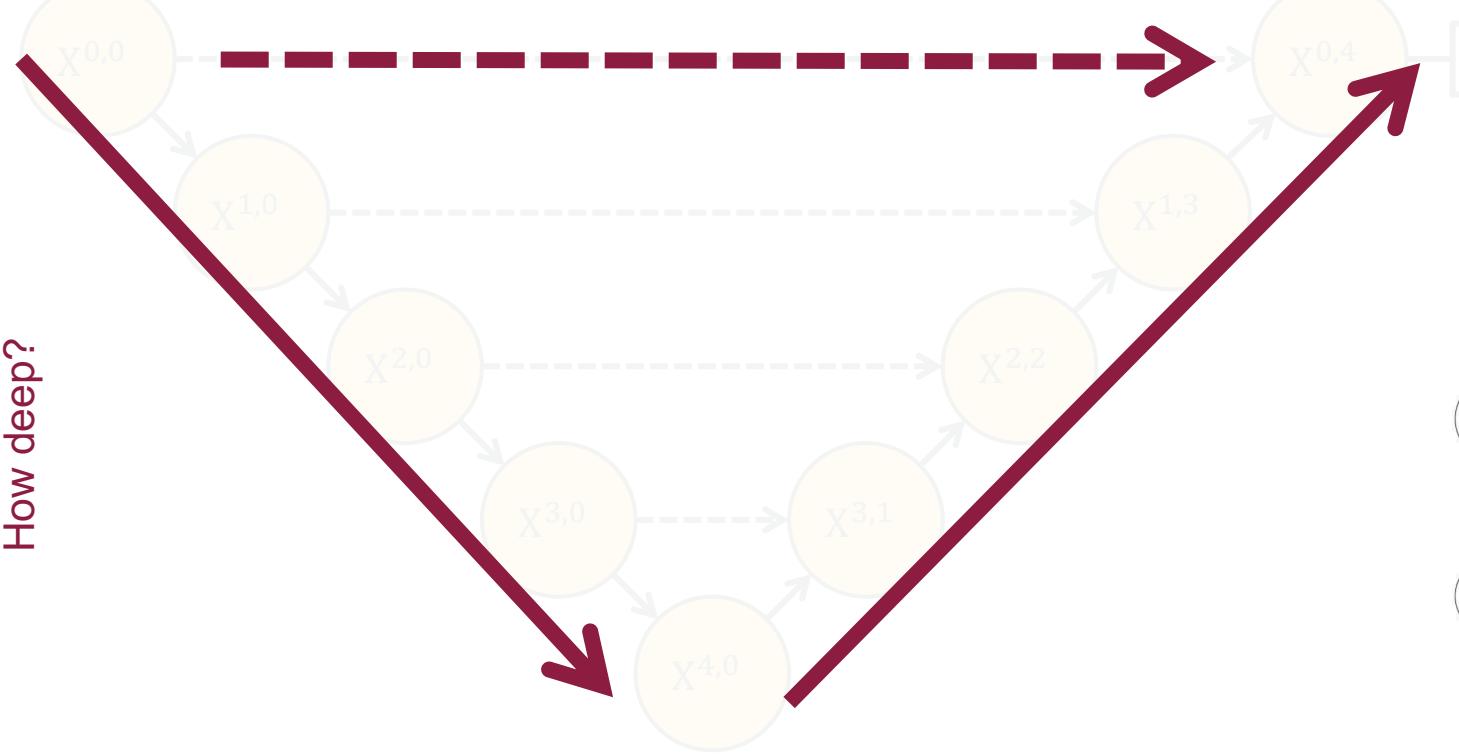


(Zhao, 2017)



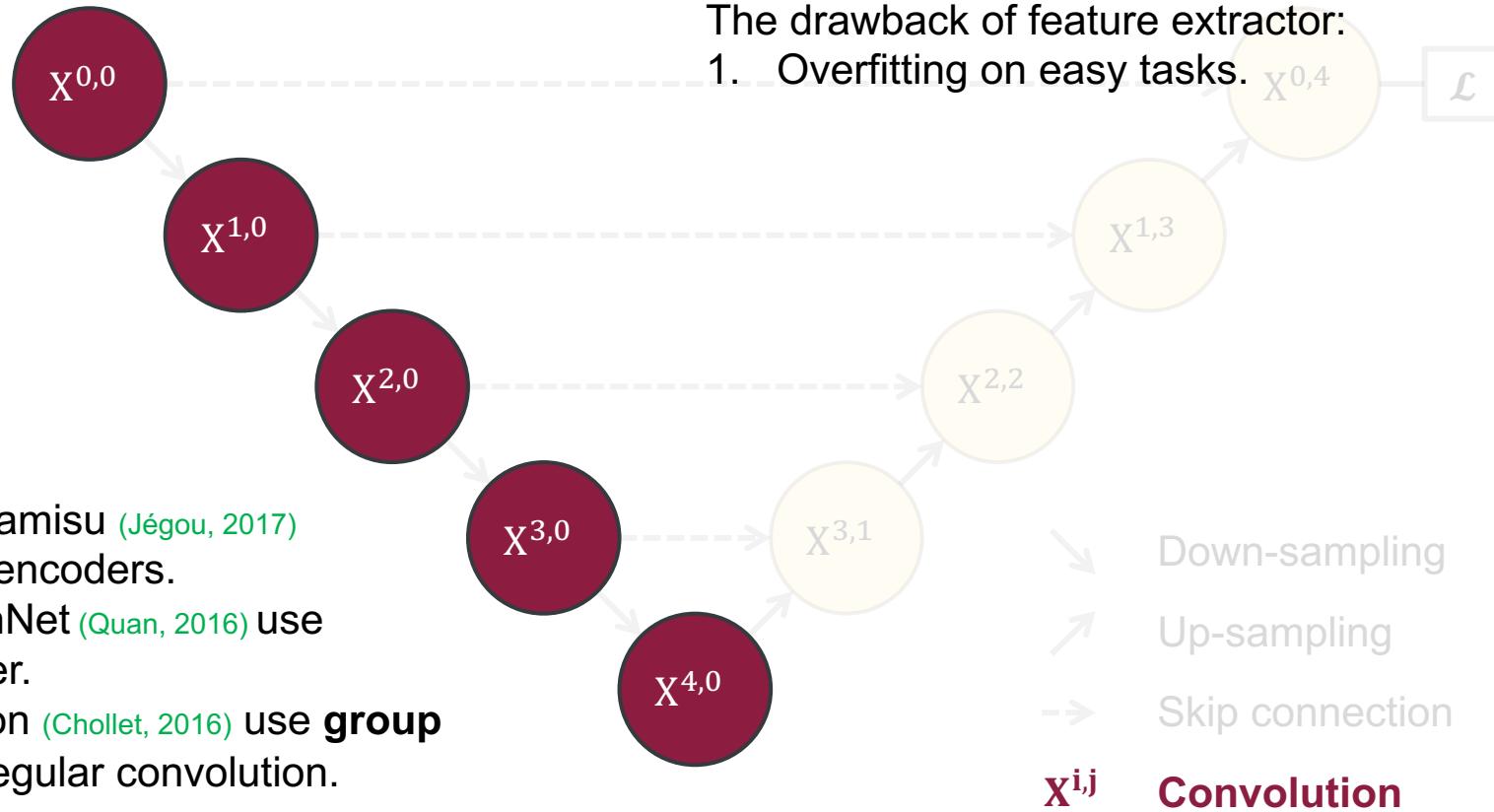


How deep?



(Jegou, 2017)

- H-DenseUNet (Li, 2017), Tiramisu (Jégou, 2017) use **dense units** in their encoders.
- PSPNet (Zhao, 2017), FusionNet (Quan, 2016) use **residual units** as encoder.
- ResNext (Xie, 2016), Xception (Chollet, 2016) use **group convolution** instead of regular convolution.



The feature extractor is **important**:

1. Good feature representation.
2. Fast convergence speed.

The drawback of feature extractor:

1. Overfitting on easy tasks.

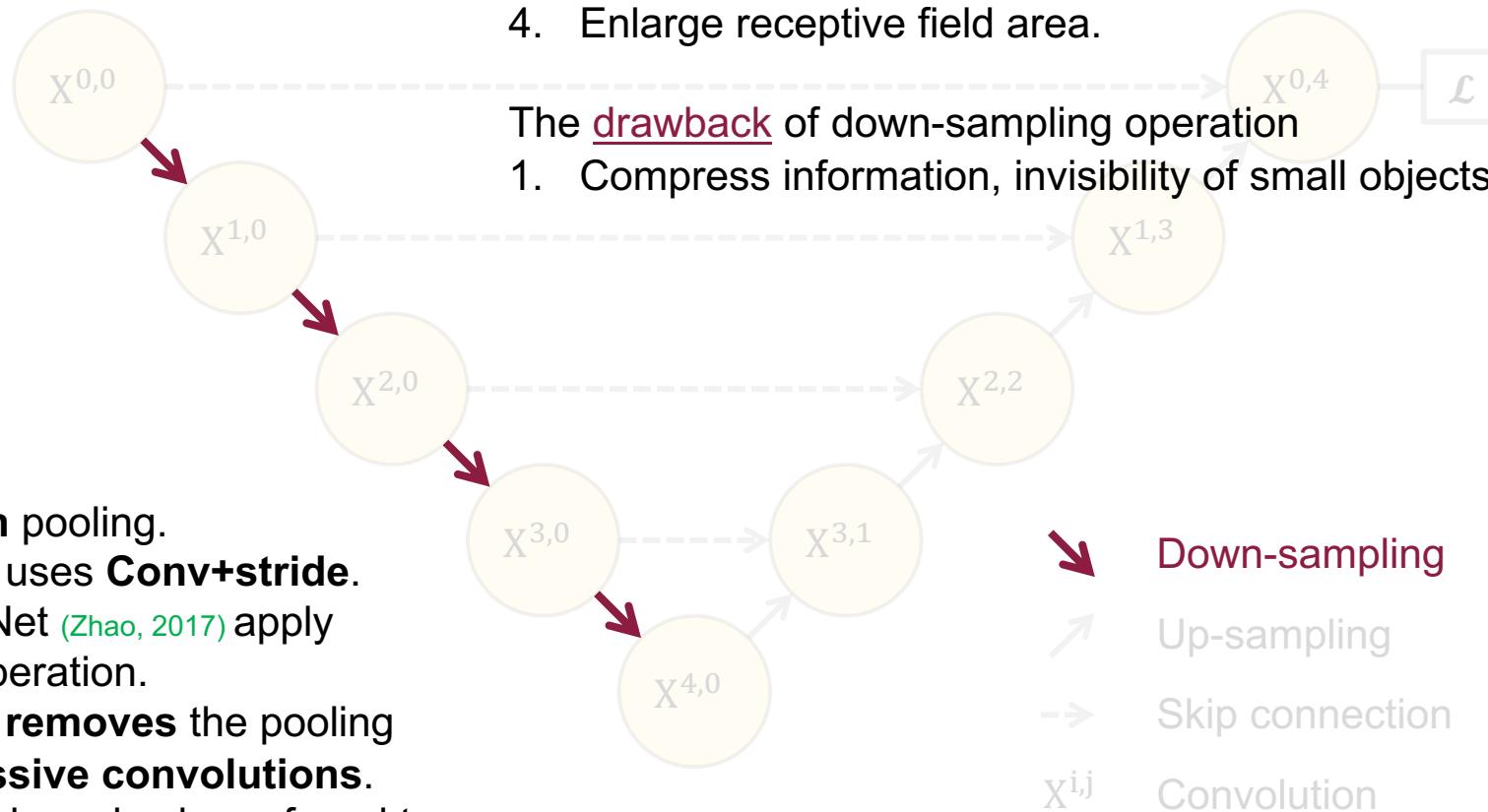
The down-sampling is **important**:

1. Robust against small input variance.
2. Reduce overfitting.
3. Reduce computation cost.
4. Enlarge receptive field area.

The **drawback** of down-sampling operation

1. Compress information, invisibility of small objects

- **Max vs. Ave vs. L2-norm** pooling.
- ALL-CNN (Springenberg, 2015) uses **Conv+stride**.
- DeepLab (Chen, 2017), PSPNet (Zhao, 2017) apply **dilated convolutional** operation.
- HyperDenseNet (Dolz, 2018) **removes** the pooling layers, only leave **successive convolutions**.
- Discarding pooling layers has also been found to be important in training **VAEs** or **GANs**.



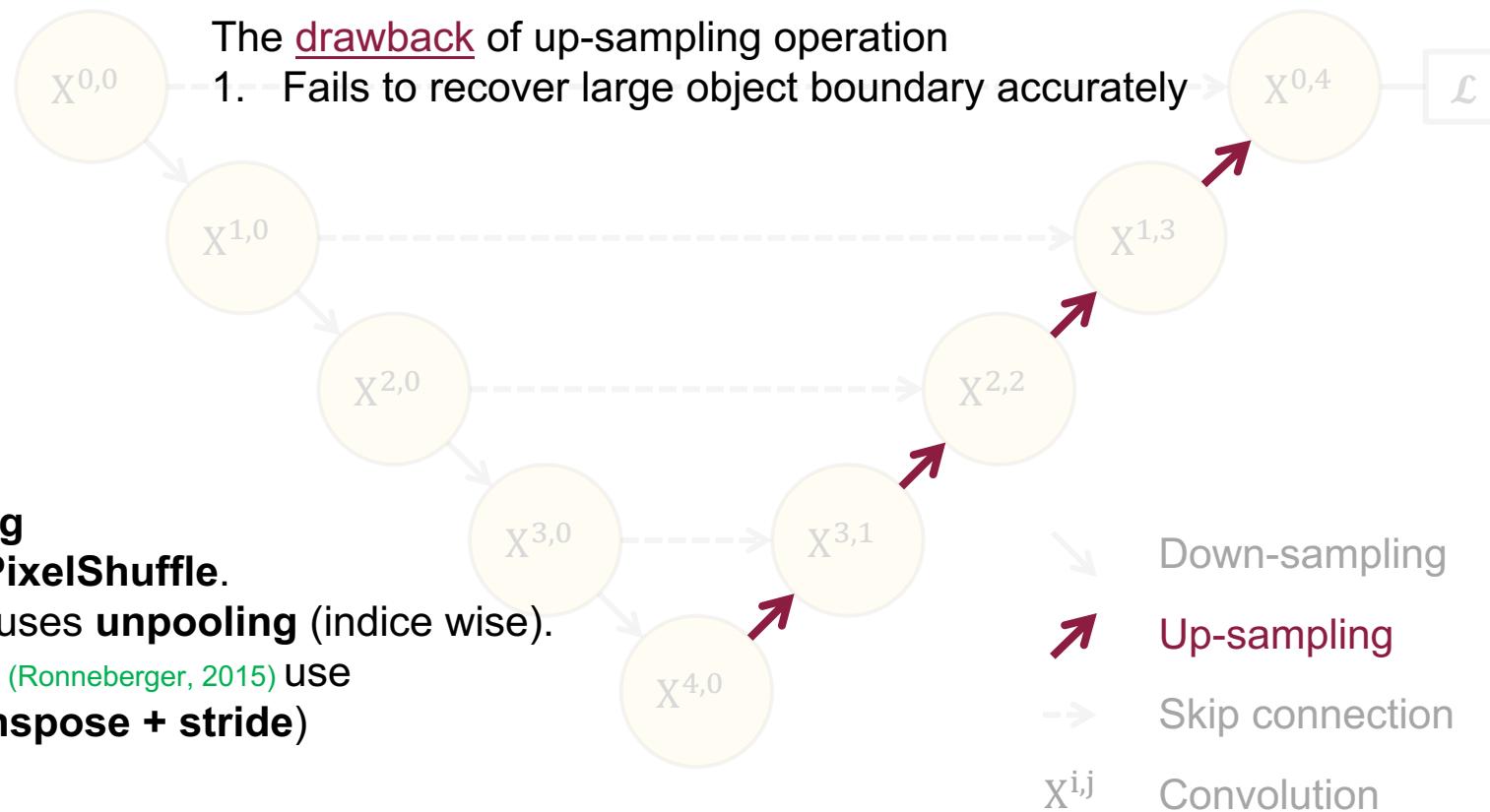
The up-sampling is important:

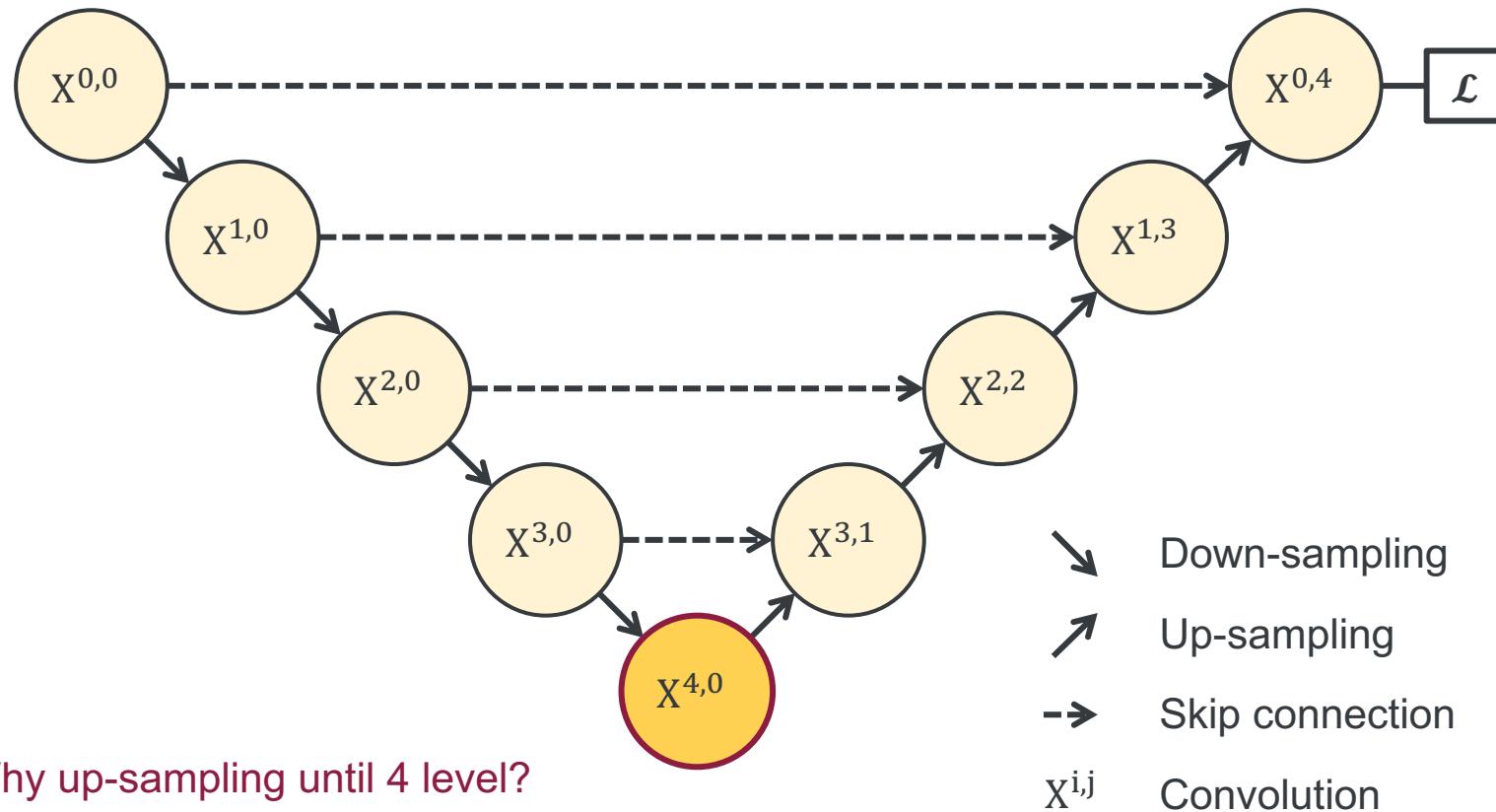
1. Recovers lost resolution in down-sampling
2. Guides encoder to select important information

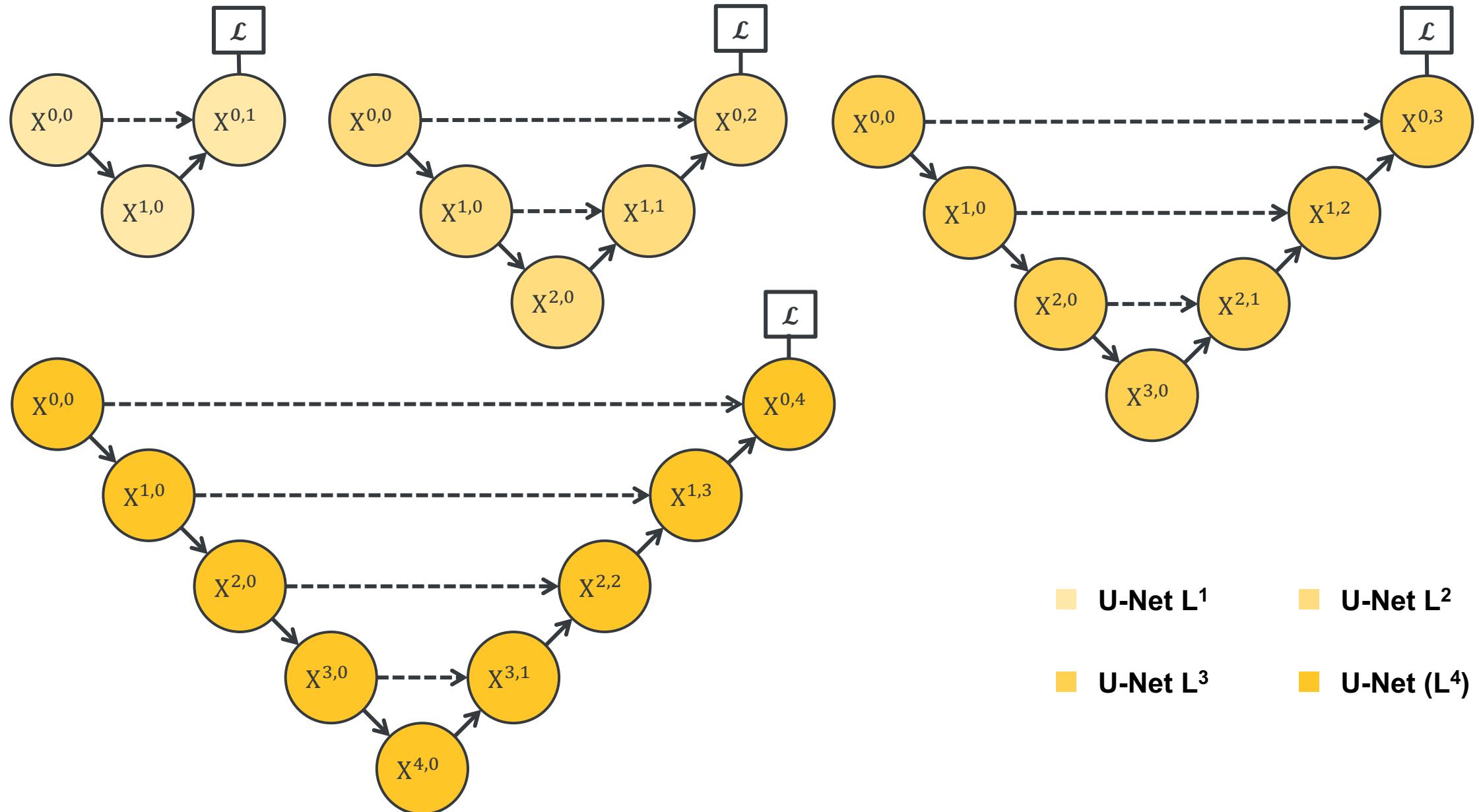
The drawback of up-sampling operation

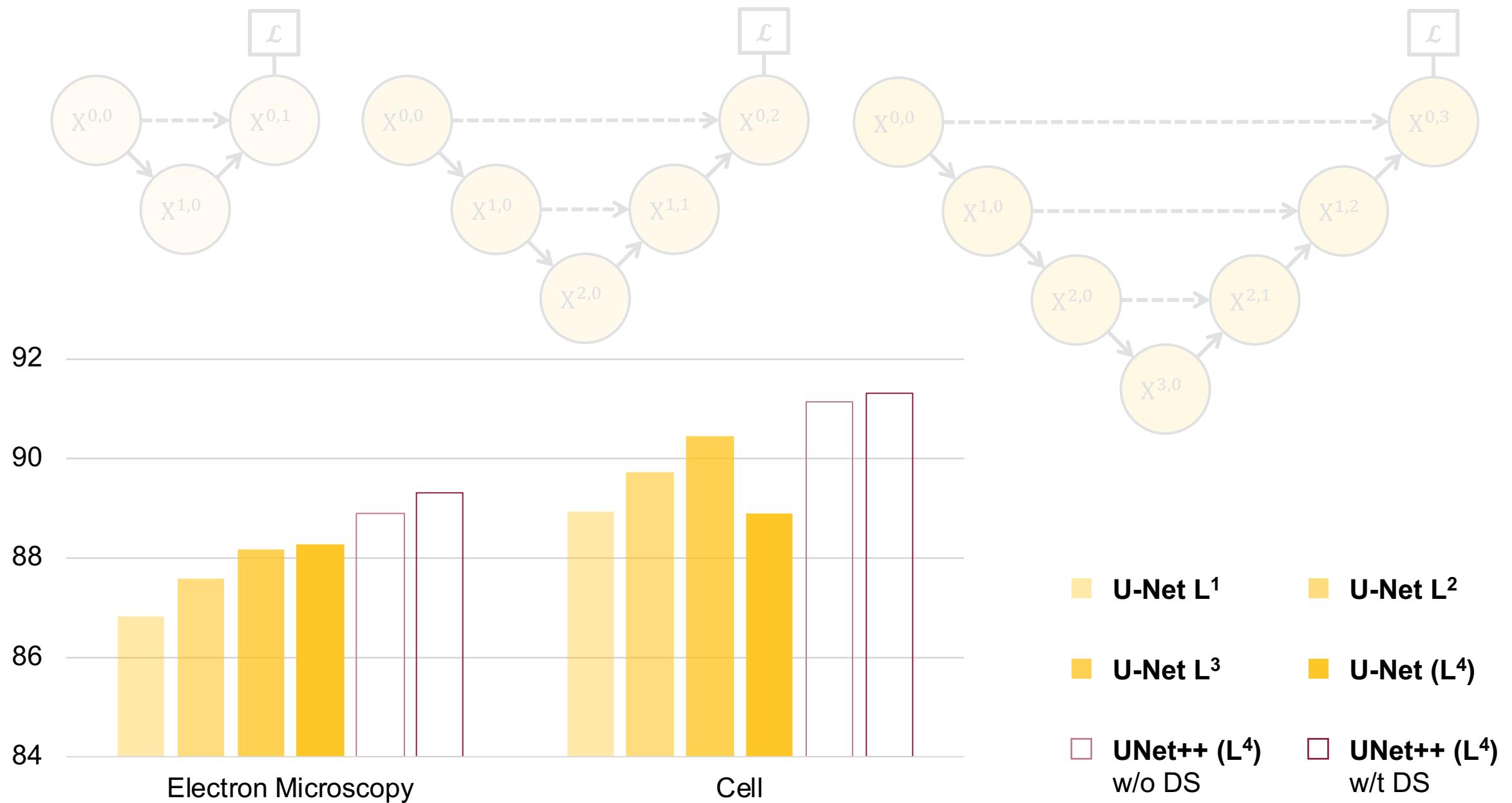
1. Fails to recover large object boundary accurately

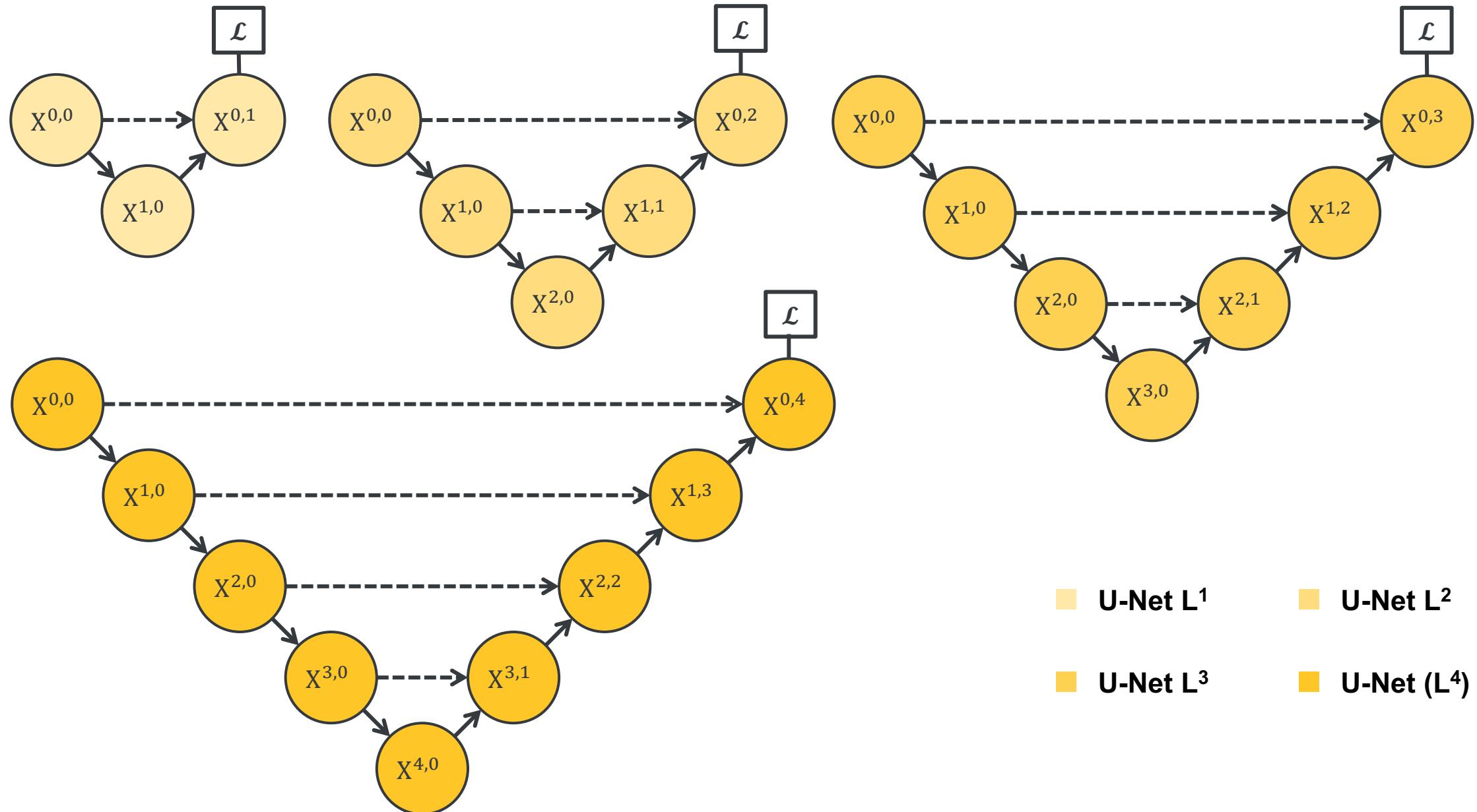
- Up-sampling by **repeating**
- PixelDCL (Gao, 2017) uses **PixelShuffle**.
- SegNet (Badrinarayanan, 2016) uses **unpooling** (indice wise).
- FCN (Long, 2015) and U-Net (Ronneberger, 2015) use deconvolution (**ConvTranspose + stride**)

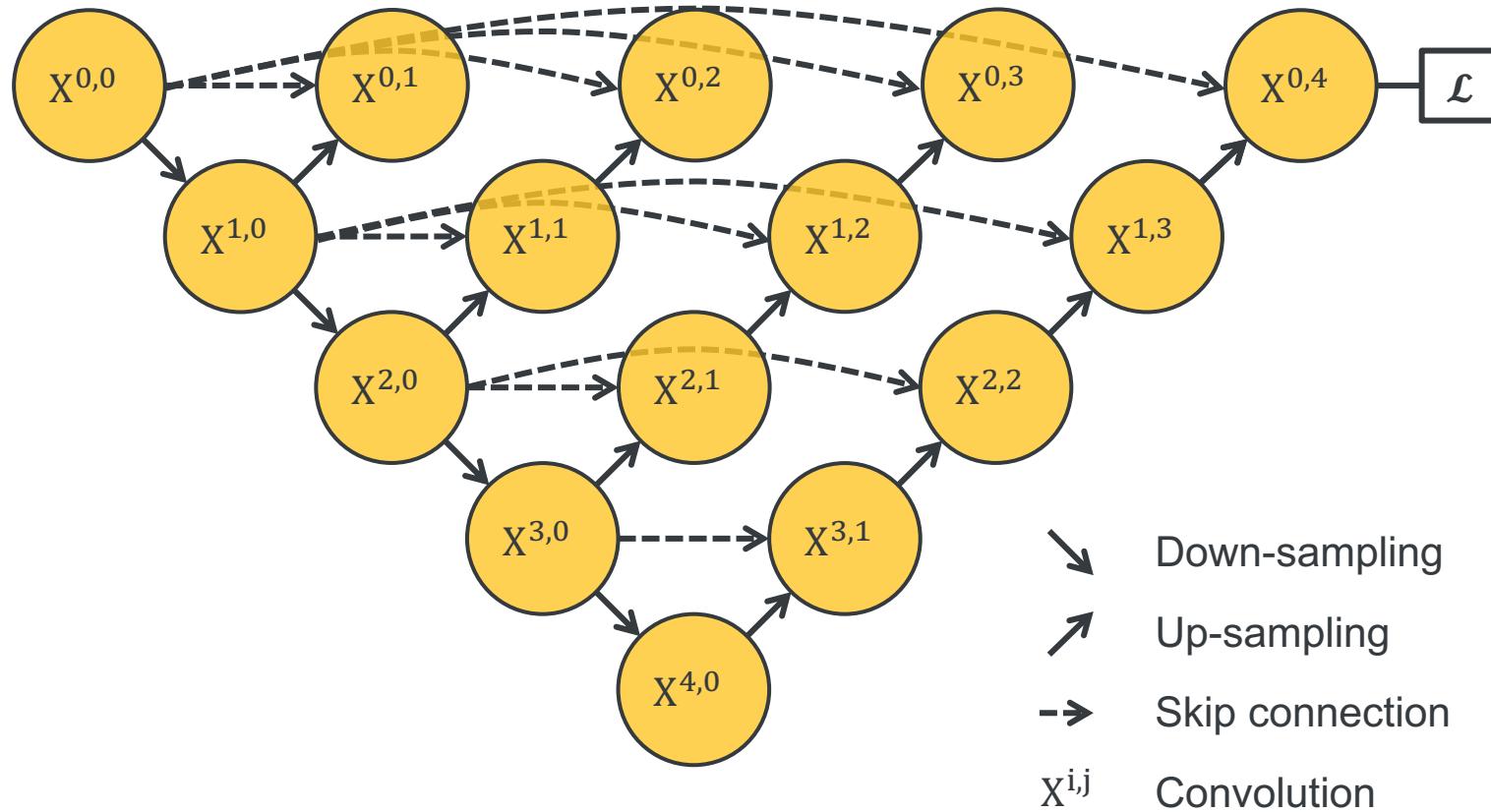


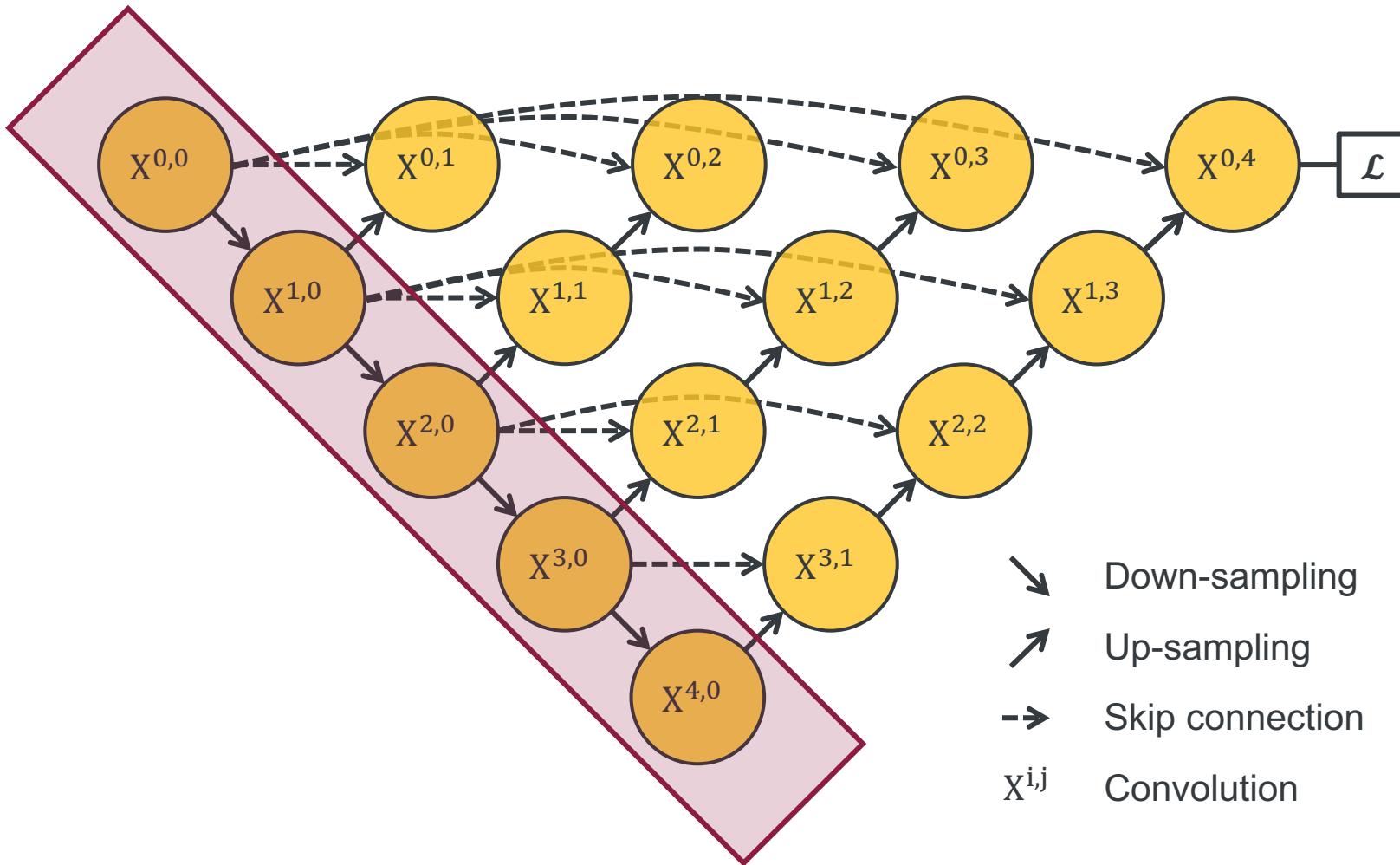


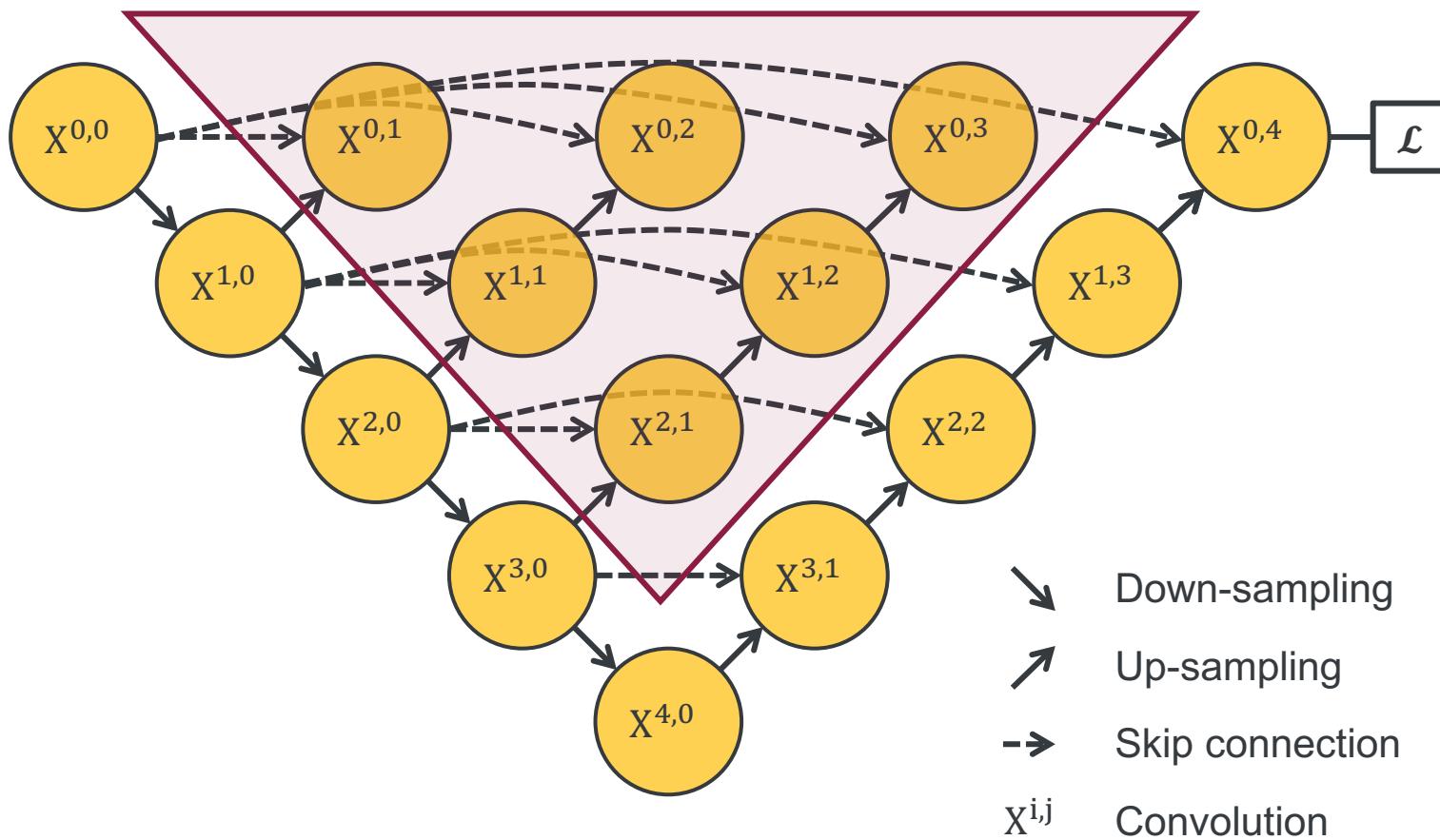


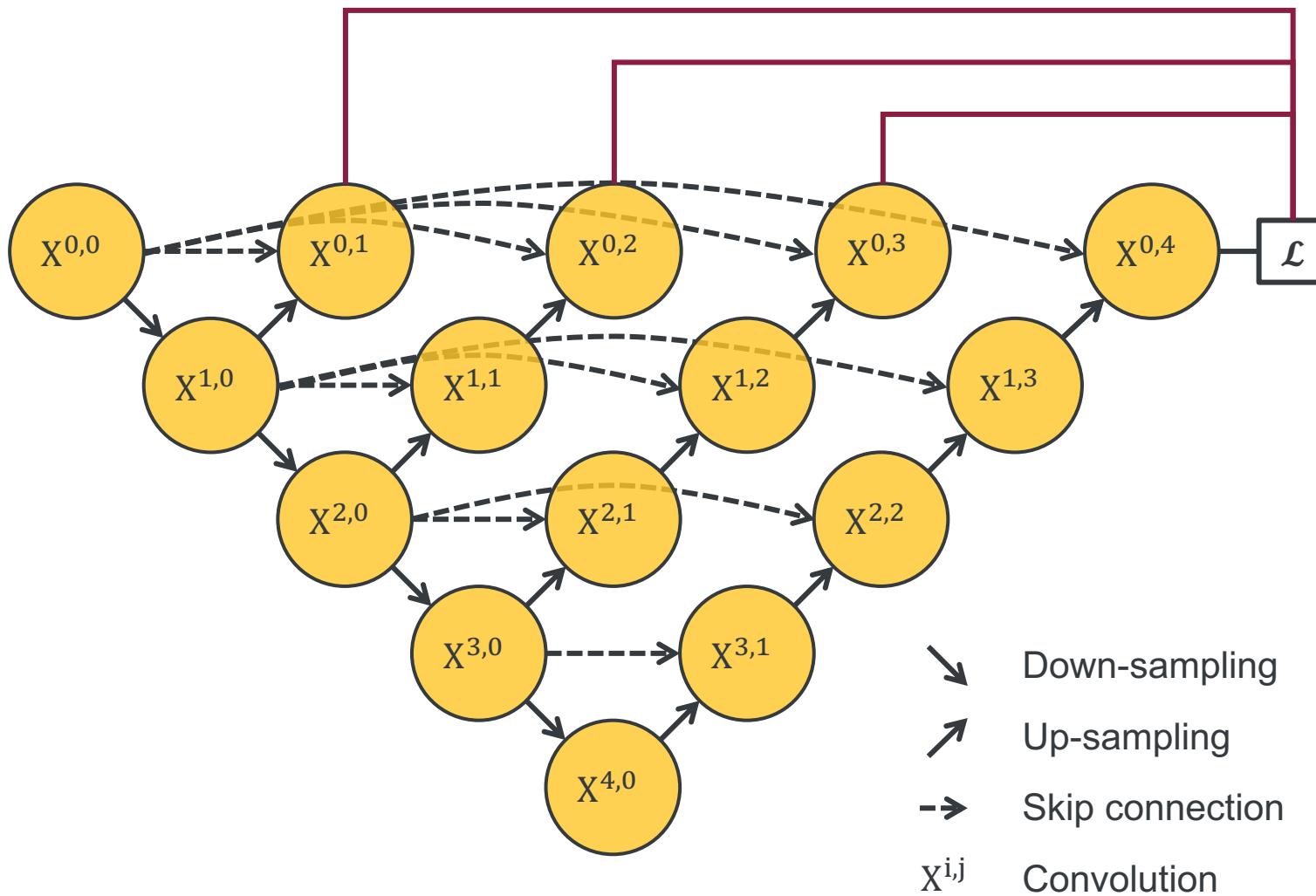


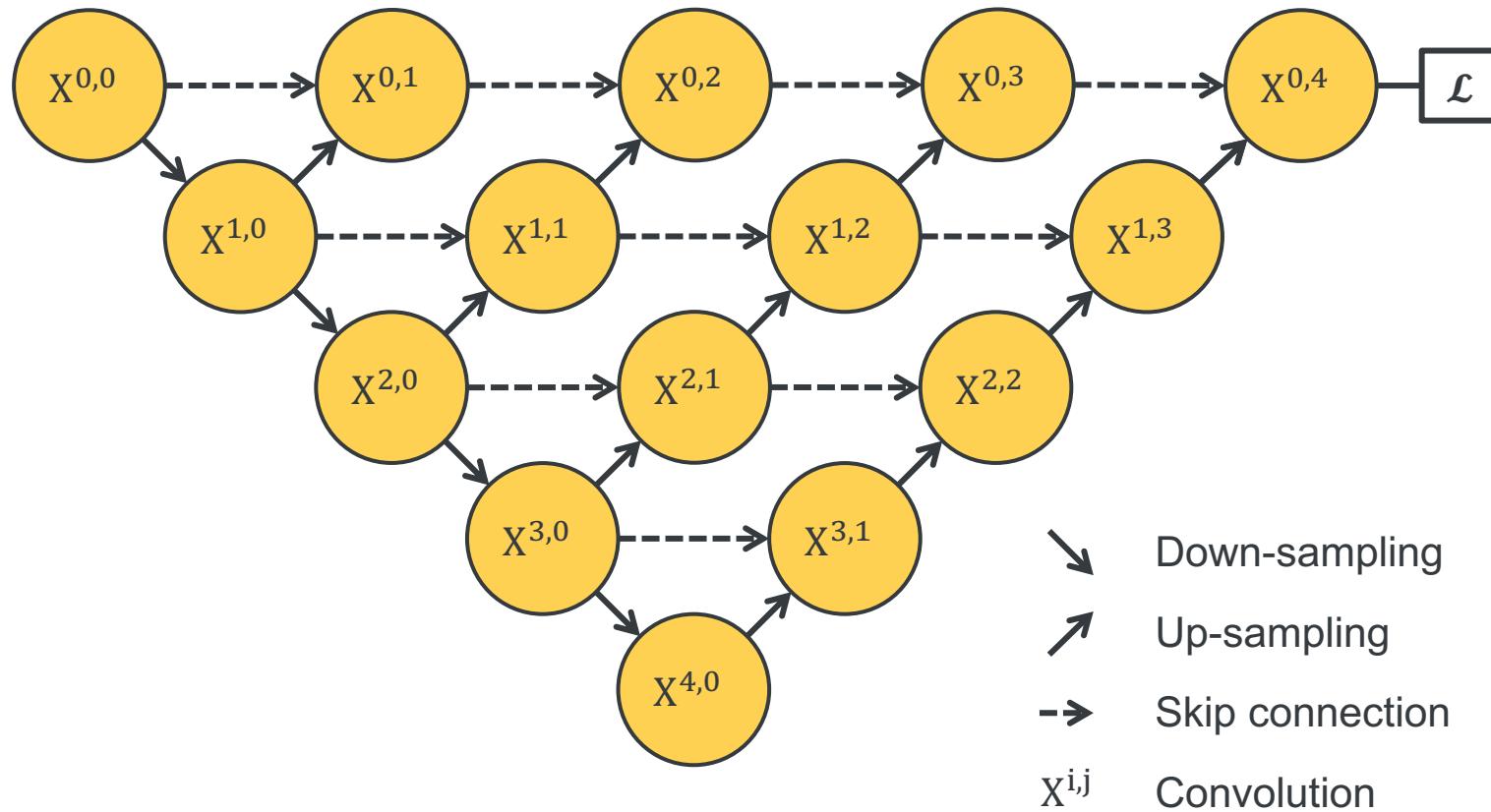


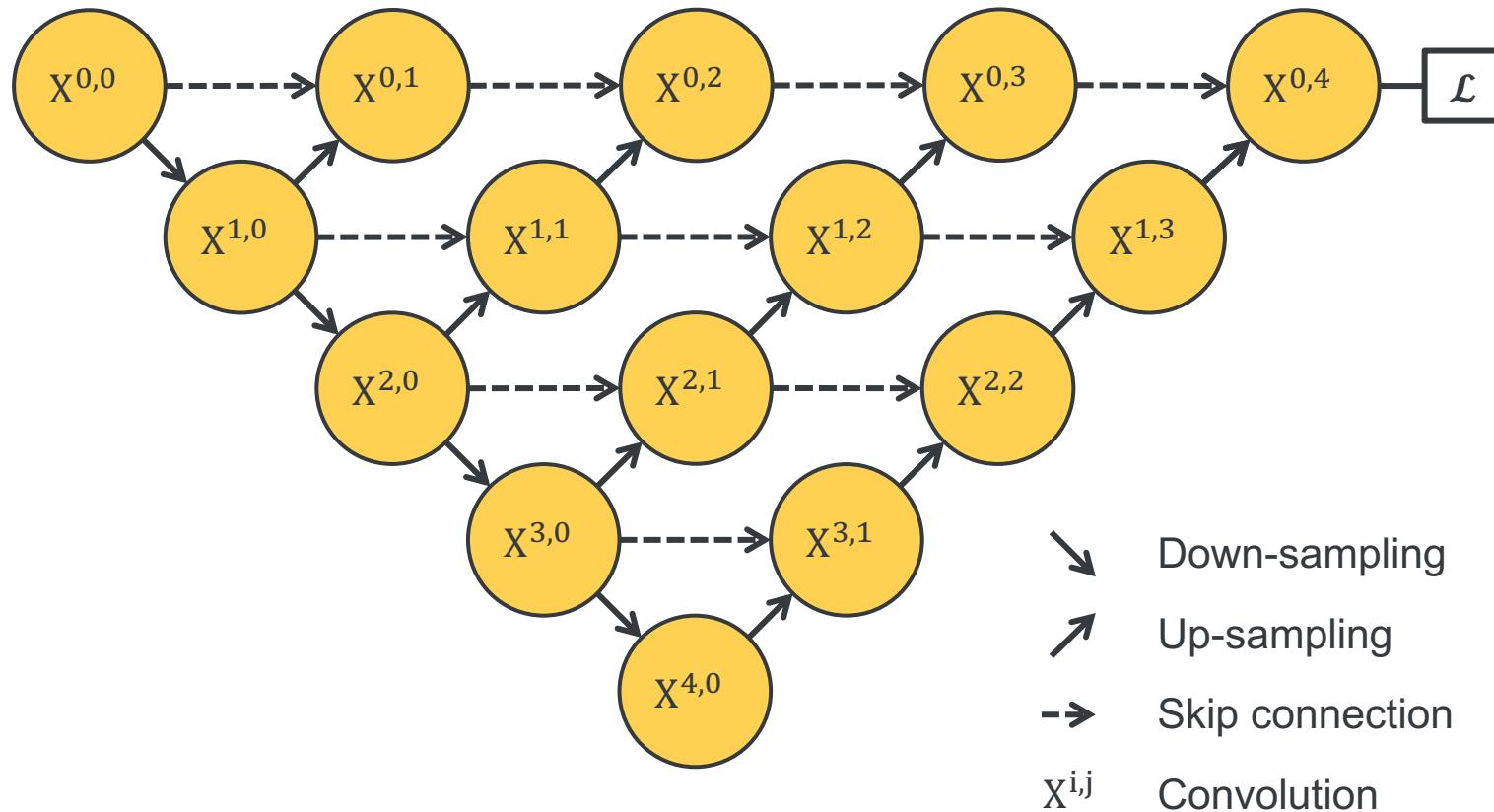




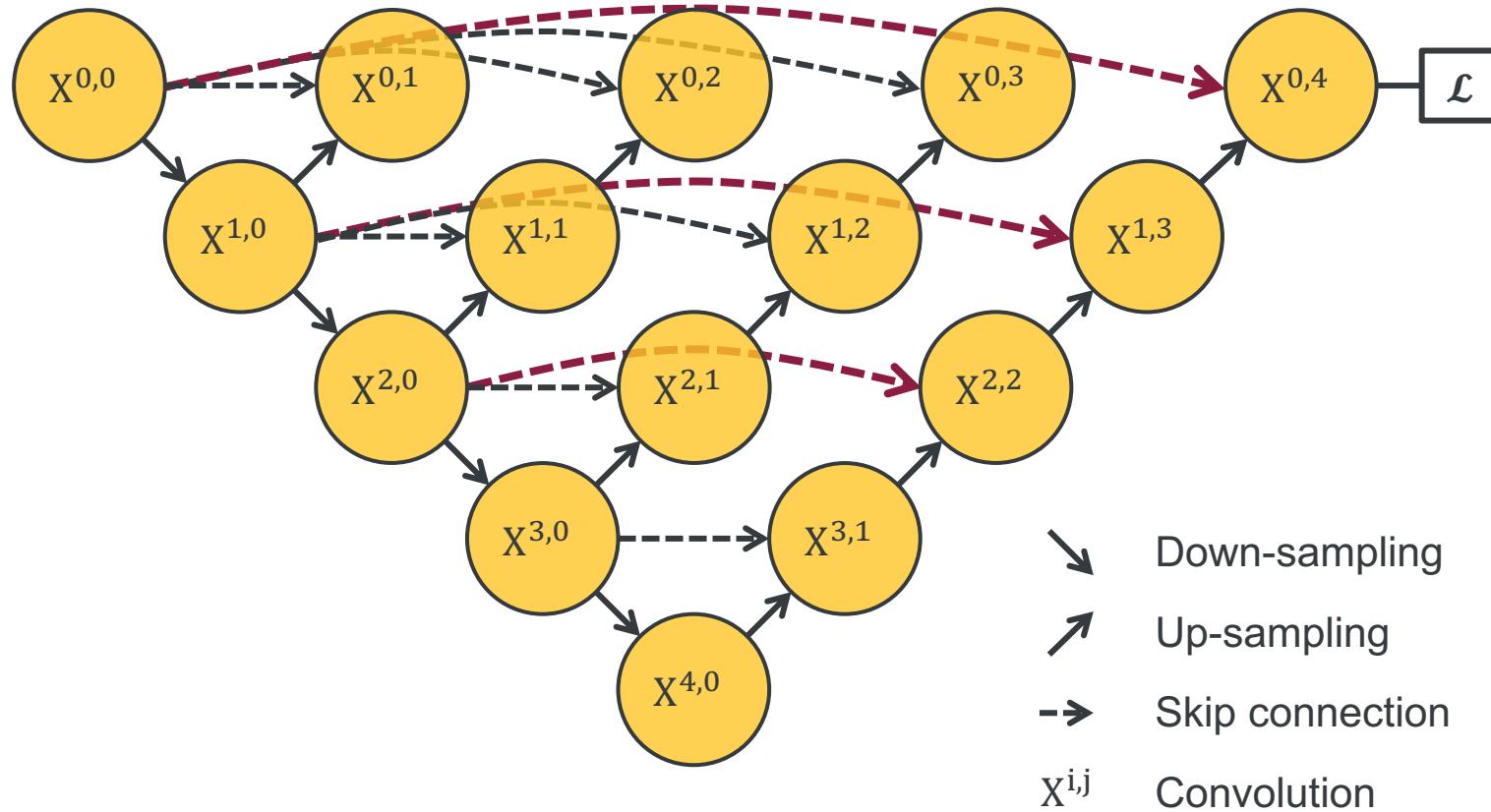






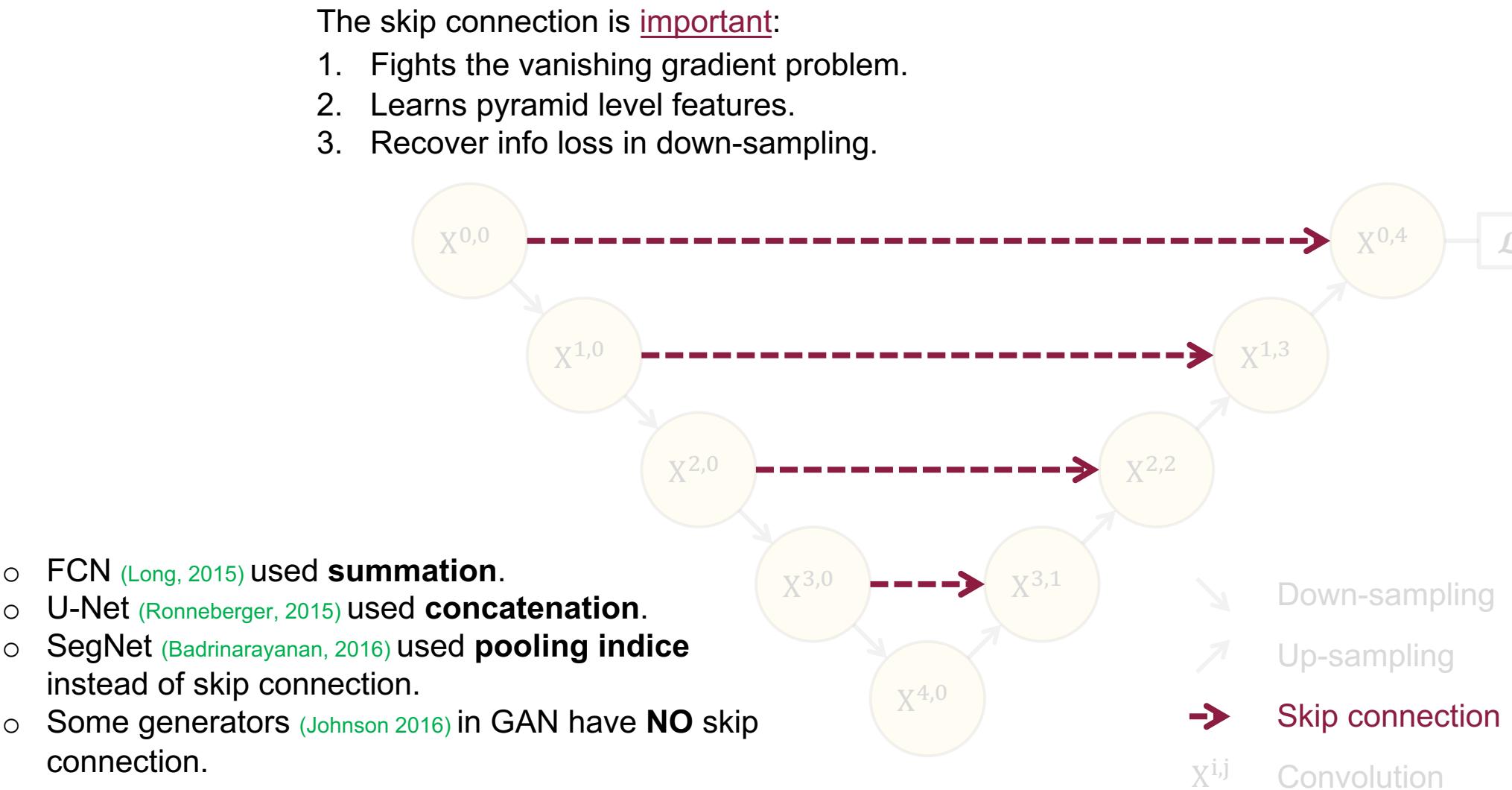


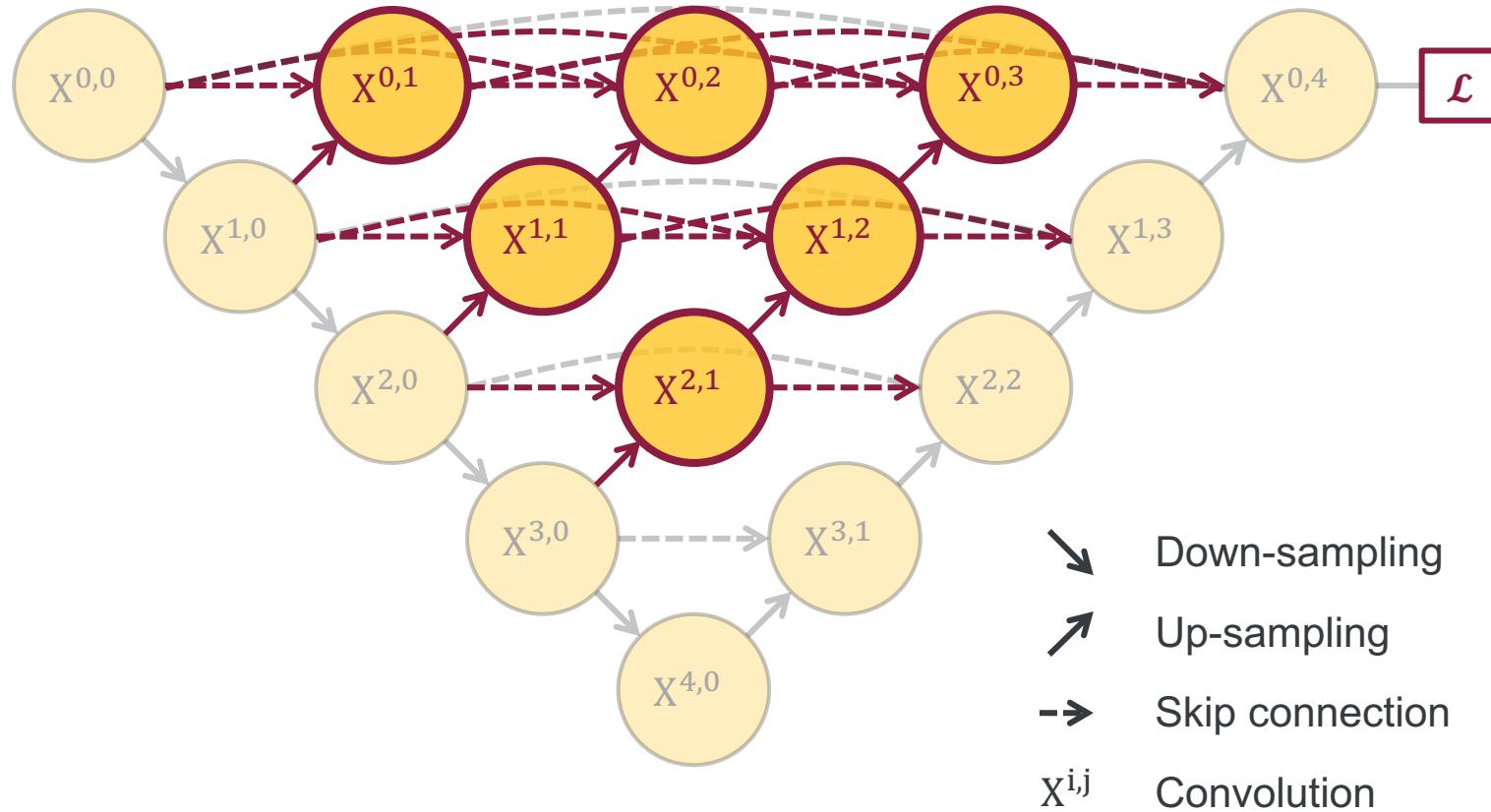
(Yu, CVPR 2018)
Deep Layer Aggregation

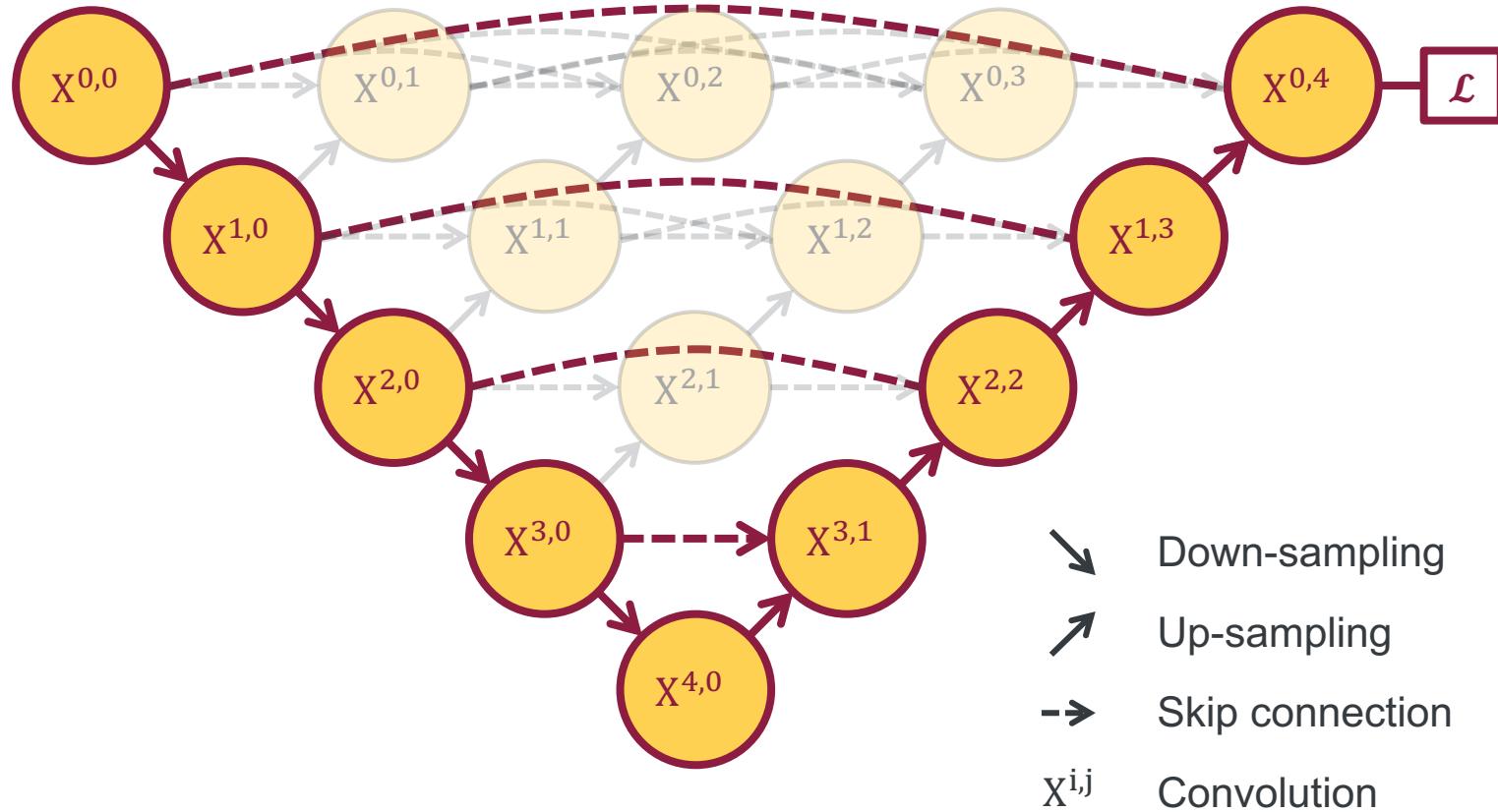


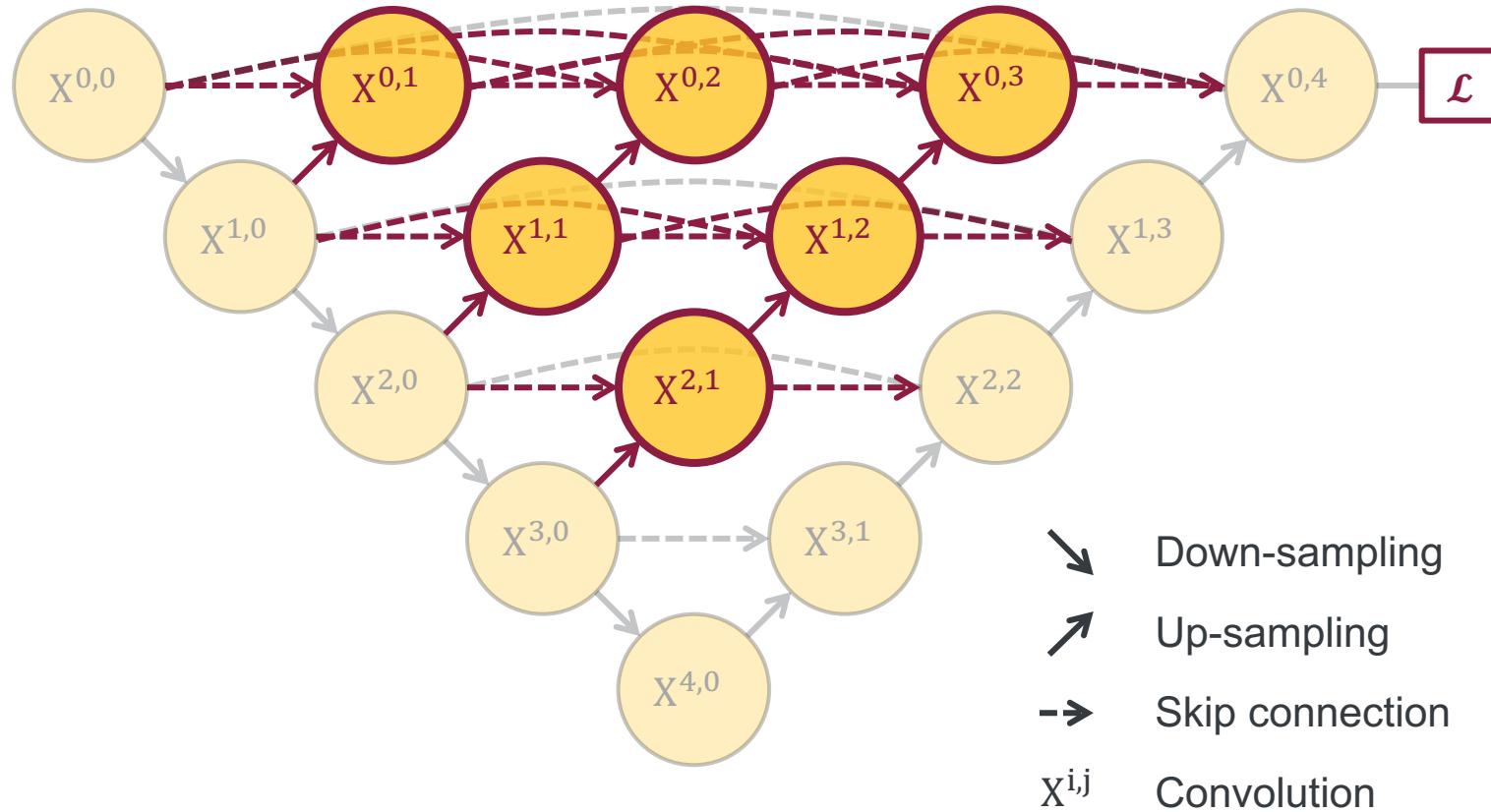
The skip connection is important:

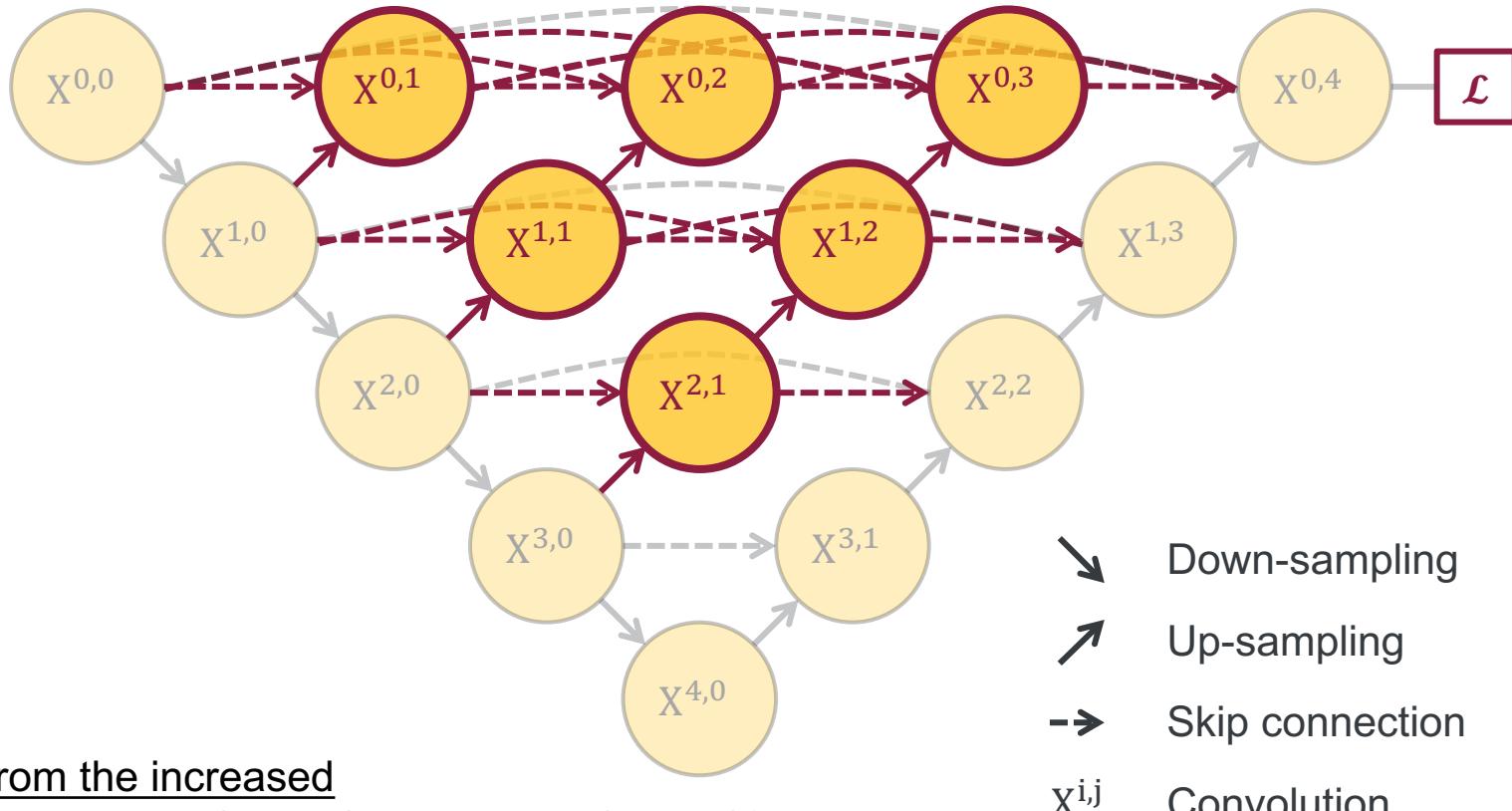
1. Fights the vanishing gradient problem.
2. Learns pyramid level features.
3. Recover info loss in down-sampling.



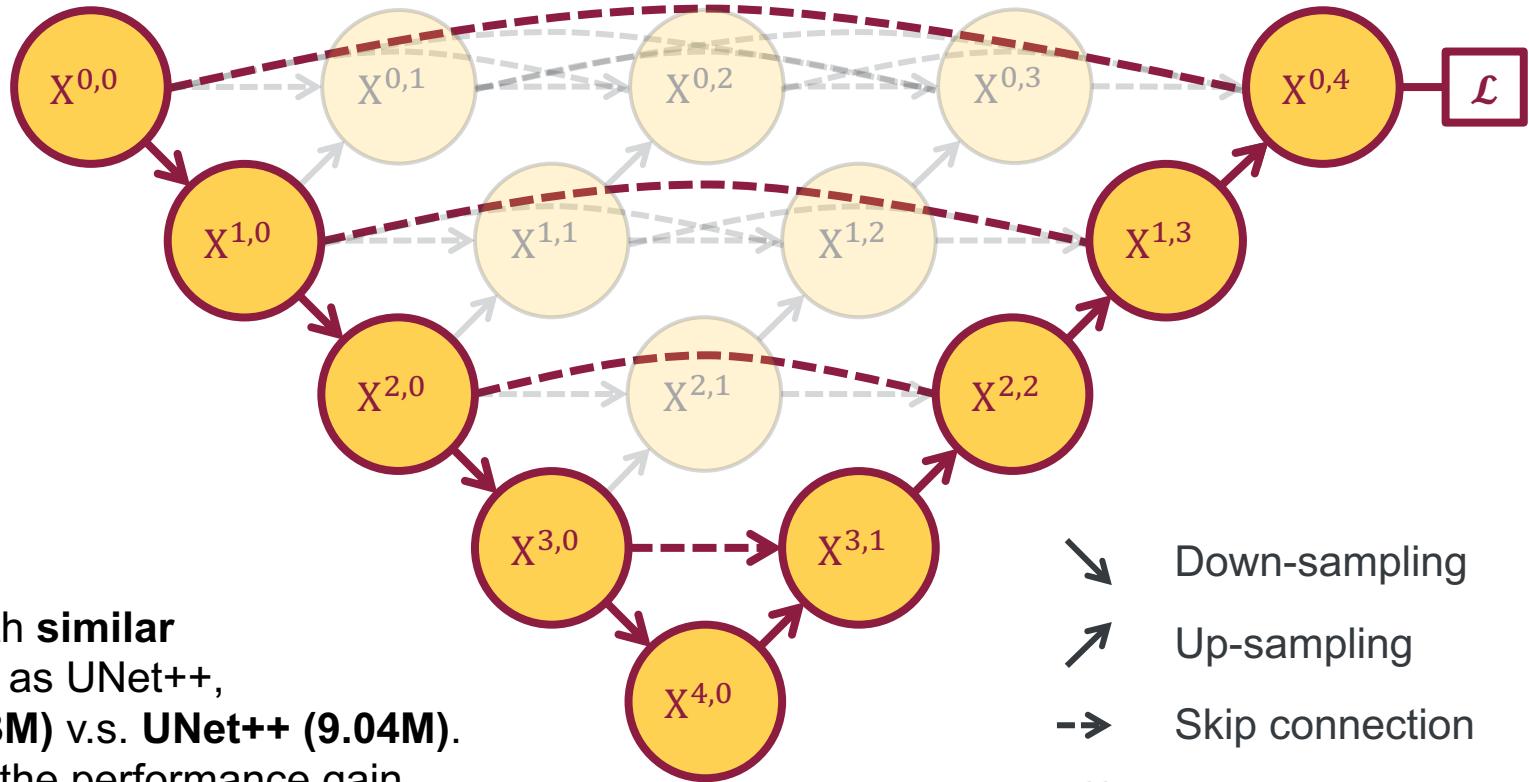








Q: Does the benefit come from the increased number of parameters? That is, U-Net (7.76M) vs. UNet++ (9.04M)?

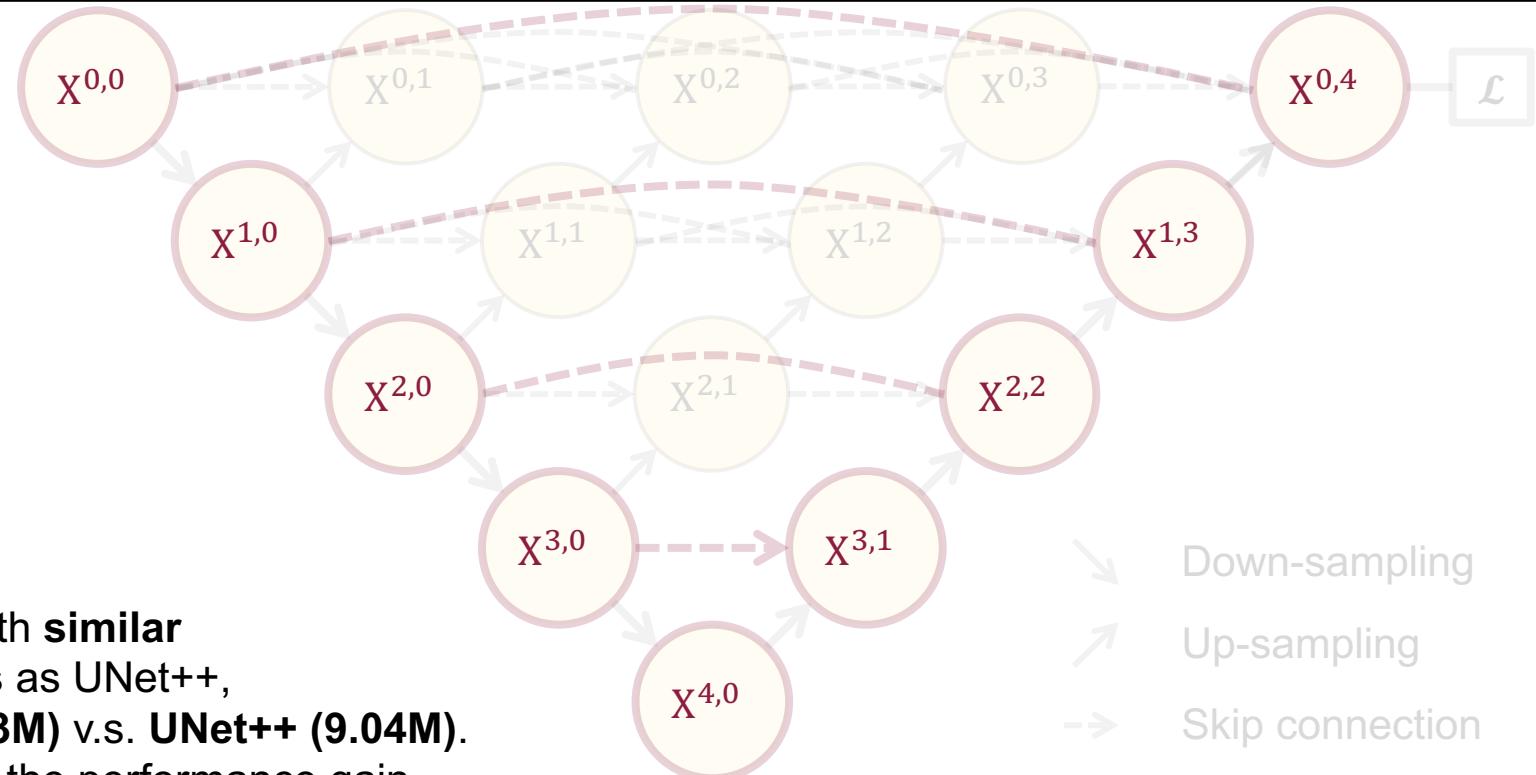


“Wide” U-Net

- Design a wide U-Net with **similar number of parameters** as UNet++, where **wide U-Net (9.13M)** v.s. **UNet++ (9.04M)**.
- This was to ensure that the performance gain yielded by UNet++ is **not** simply due to increased number of parameters.

↘ Down-sampling
 ↗ Up-sampling
 → Skip connection
 $X^{i,j}$ Convolution

Introduction	Related Works	UNet++	Results	Conclusion		
encoder / decoder		$X^{0,0} / X^{0,4}$	$X^{1,0} / X^{1,3}$	$X^{2,0} / X^{2,2}$	$X^{3,0} / X^{3,1}$	$X^{4,0} / X^{4,0}$
U-Net [7.76M]		32	64	128	256	512
“Wide” U-Net [9.13M]		35	70	140	280	560
UNet++ [9.04M]		32	64	128	256	512



“Wide” U-Net

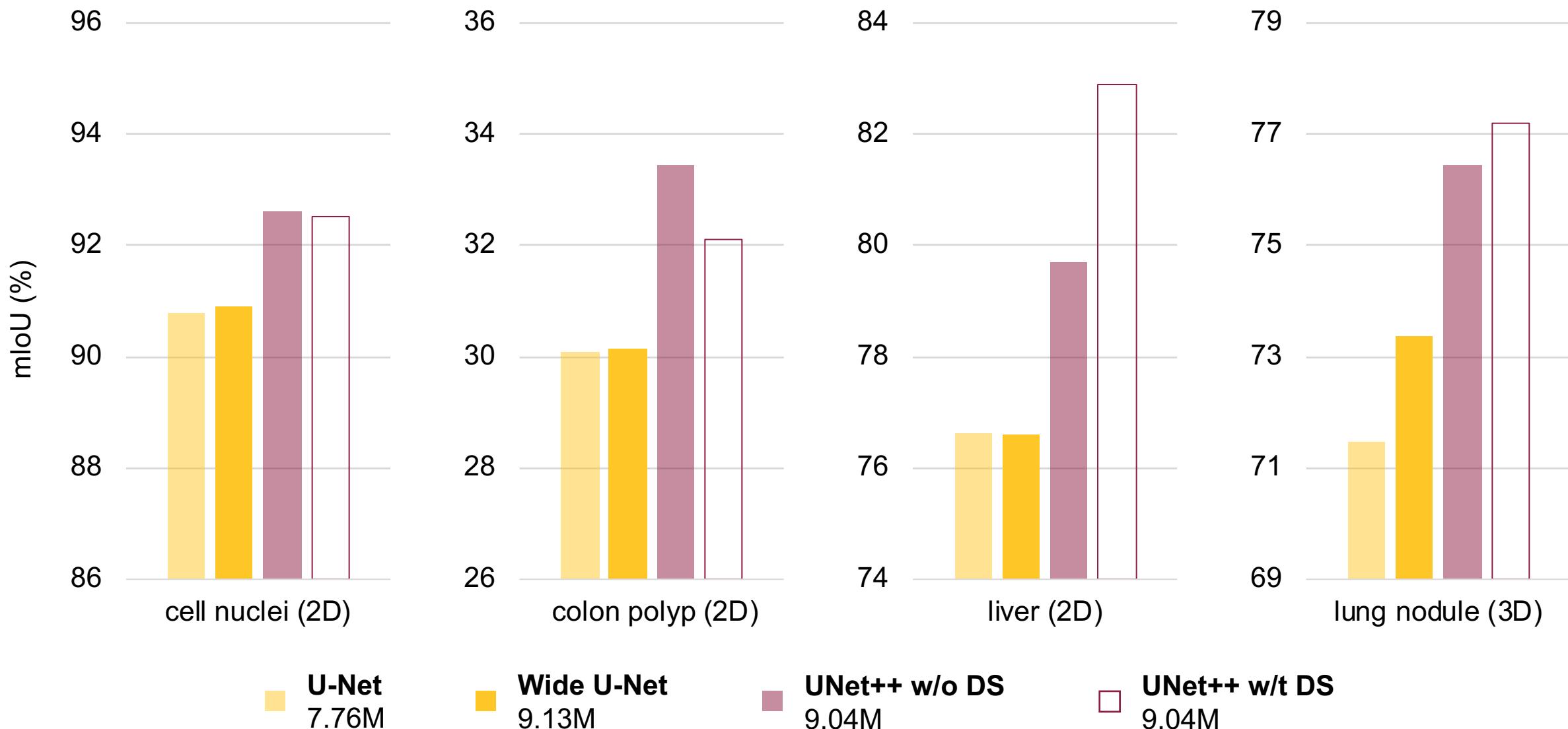
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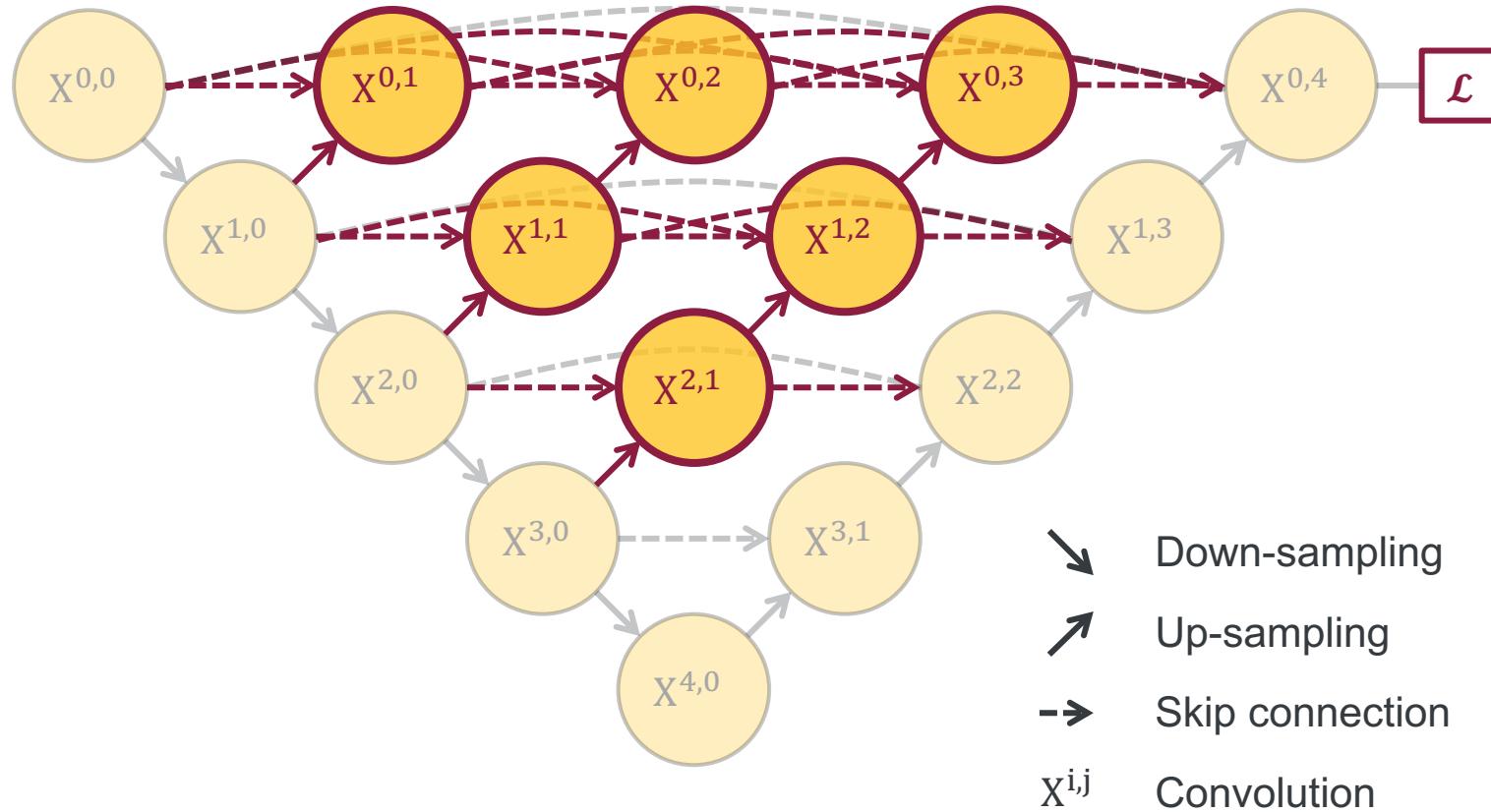
↓ Down-sampling

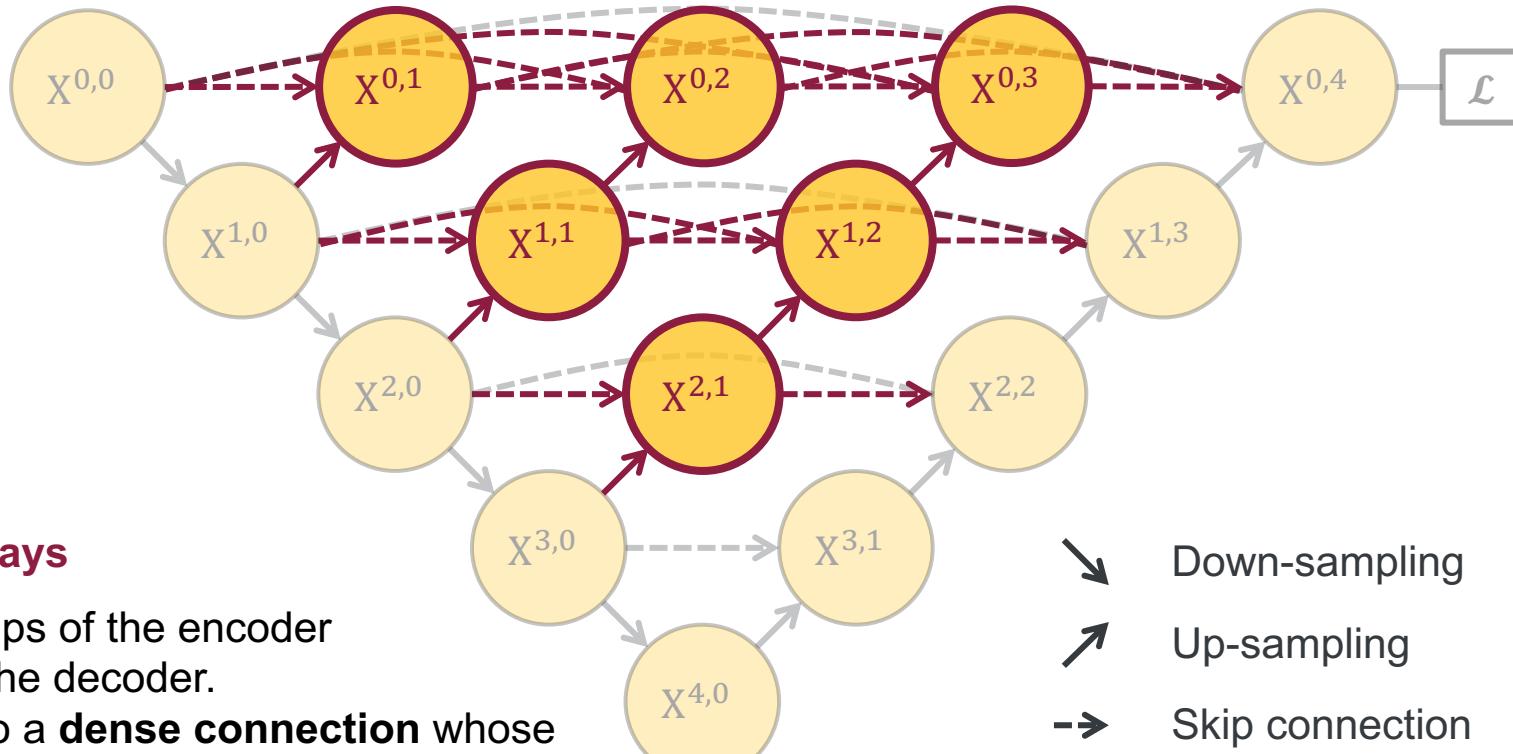
↑ Up-sampling

→ Skip connection

$X^{i,j}$ Convolution

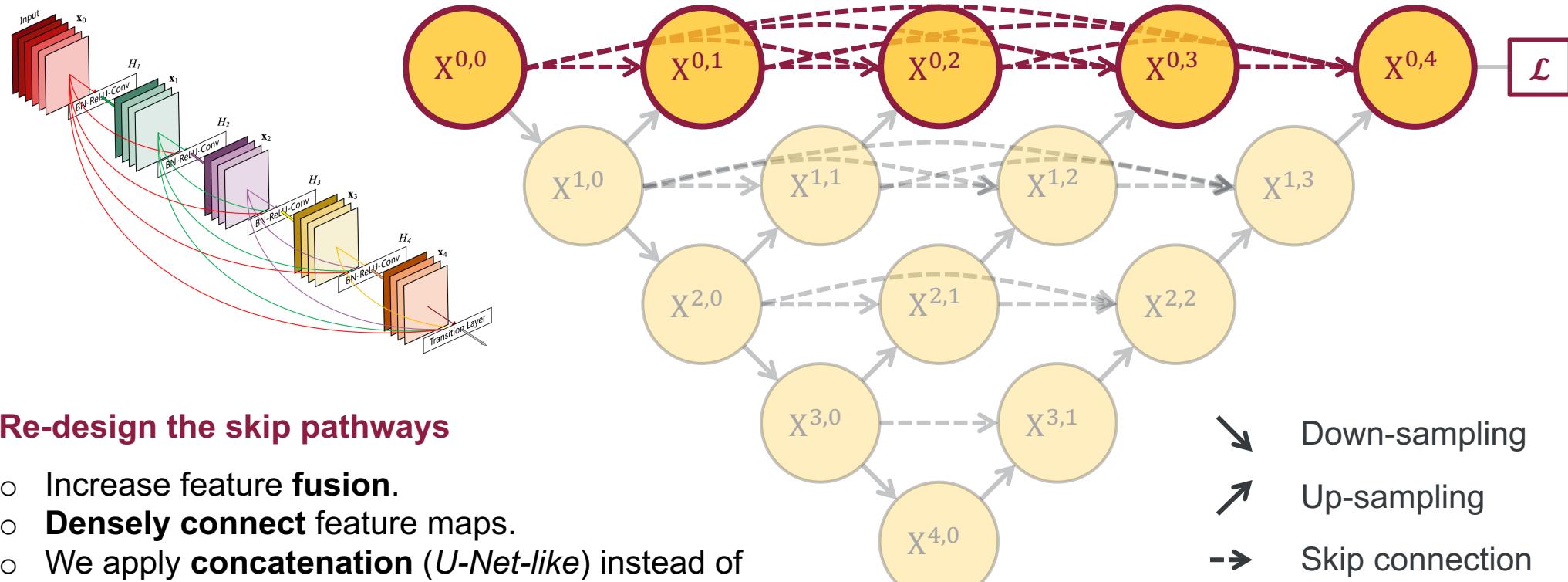


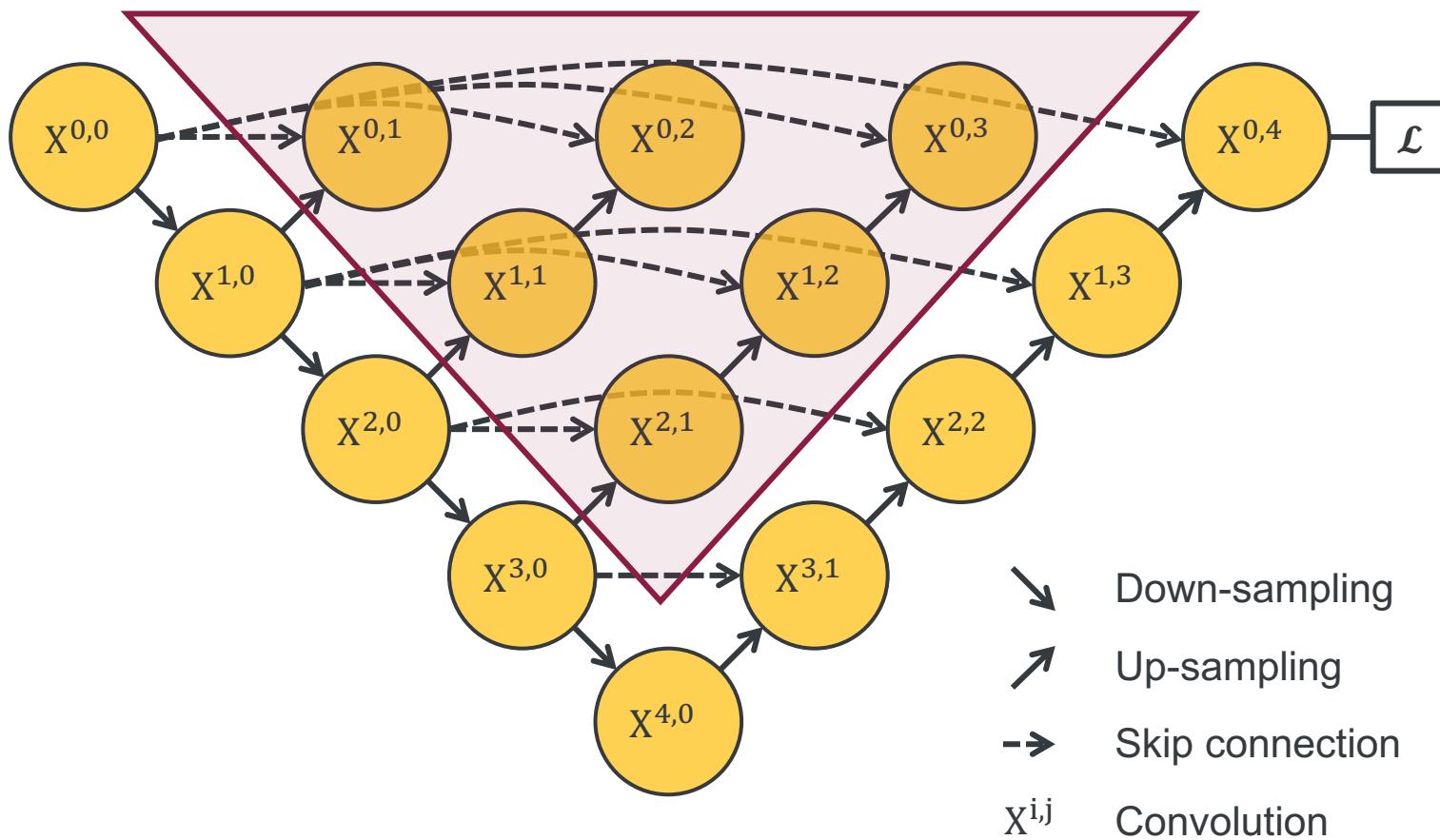


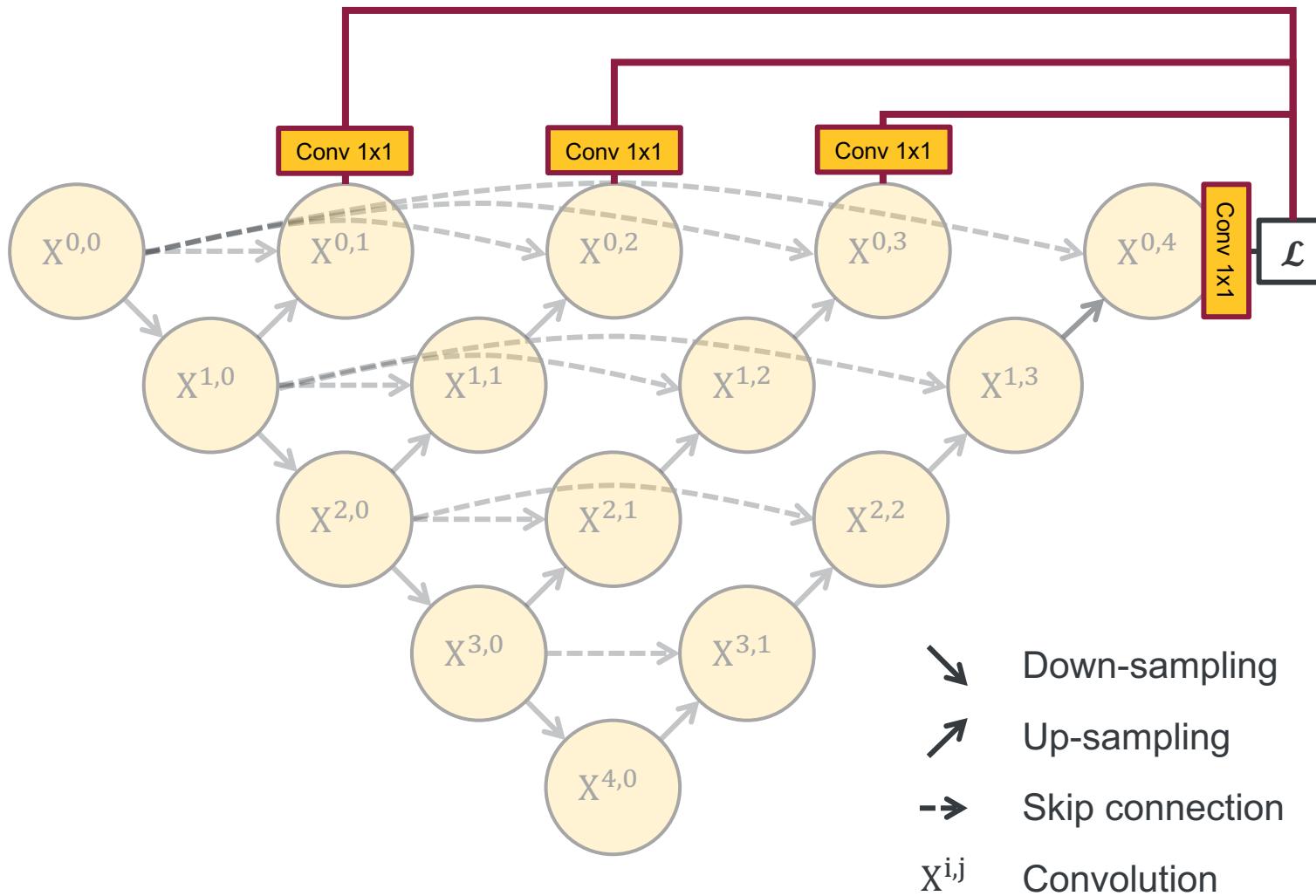


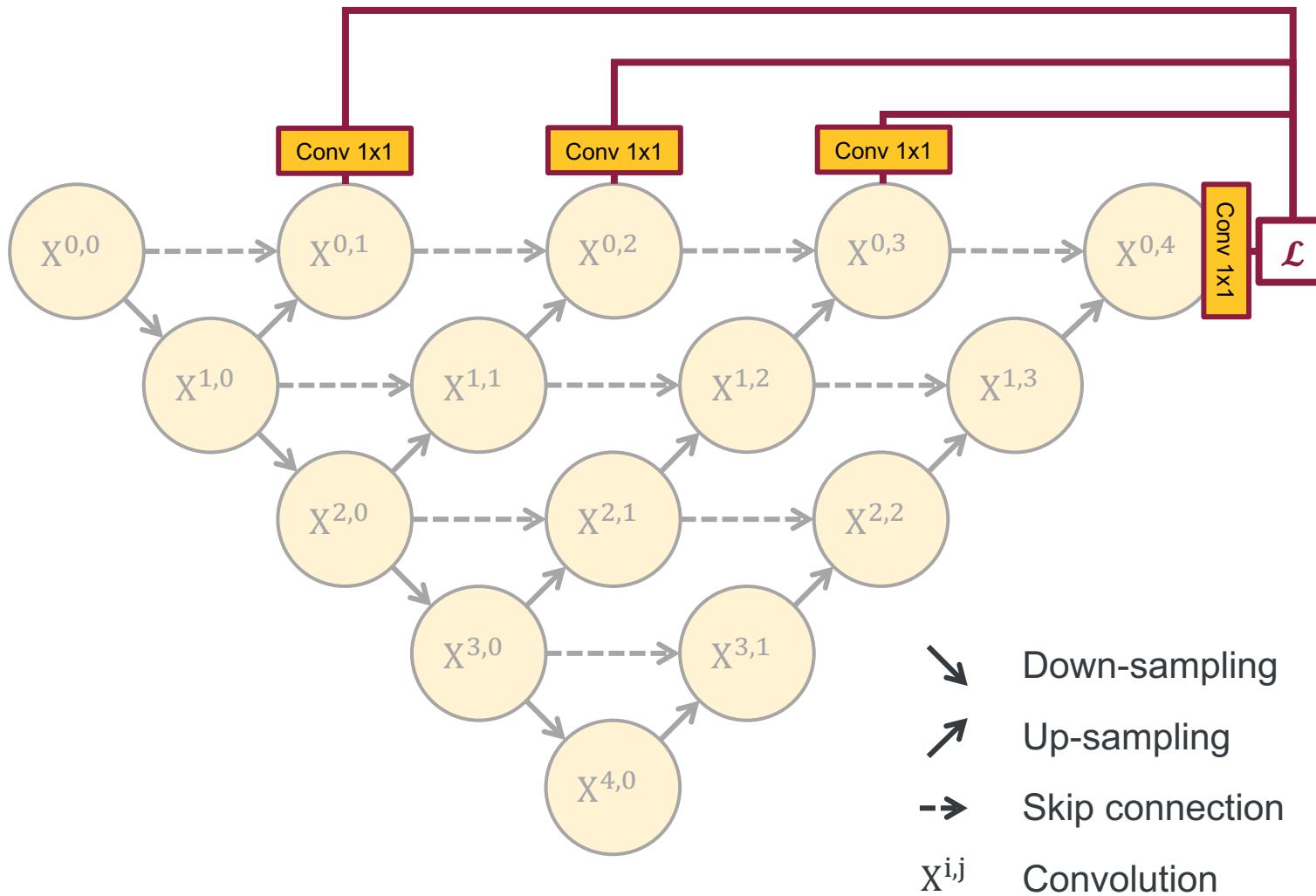
Re-design the skip pathways

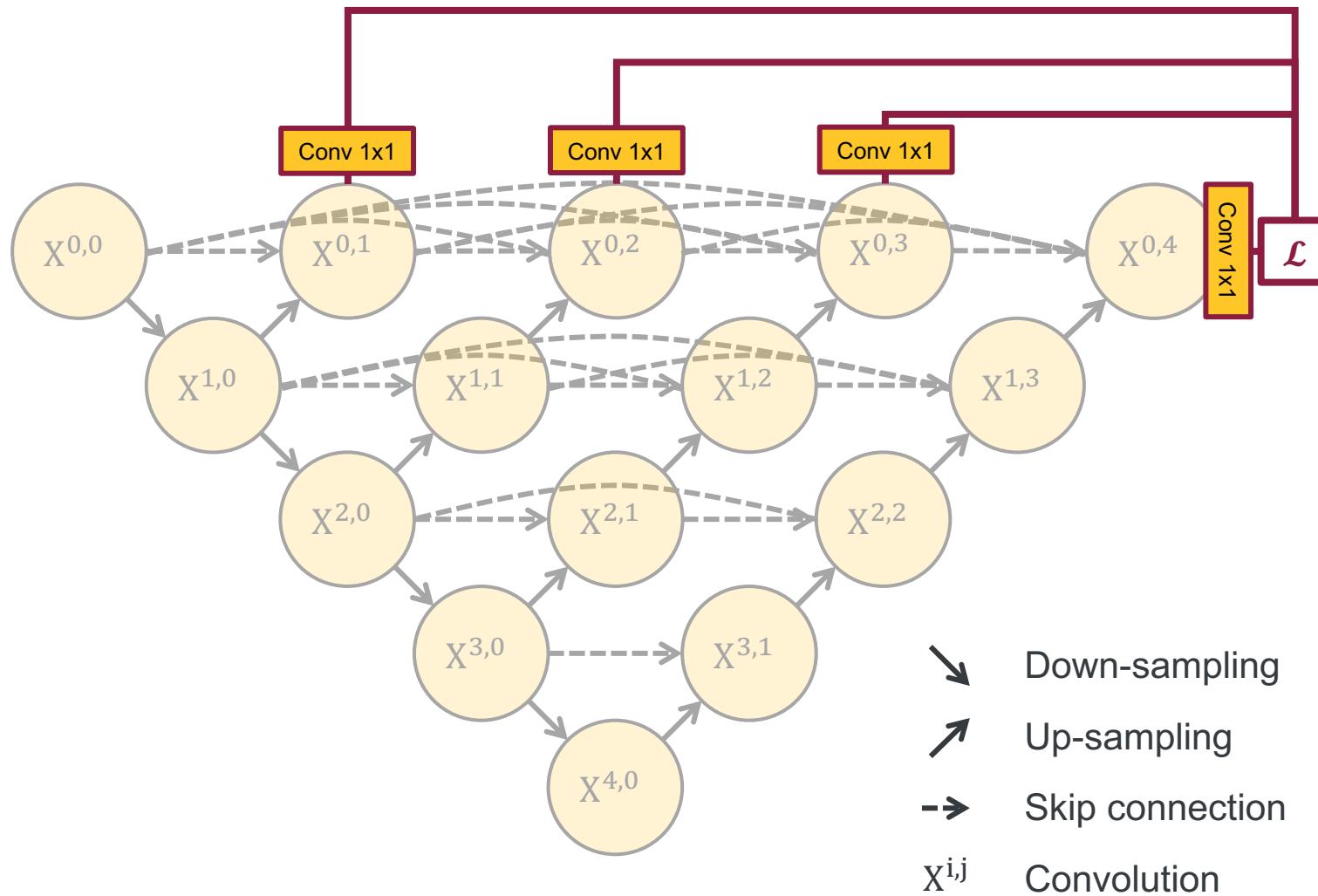
- In U-Net, the feature maps of the encoder are directly received in the decoder.
- In UNet++, they undergo a **dense connection** whose number of convolution layers depends on the **pyramid level**.

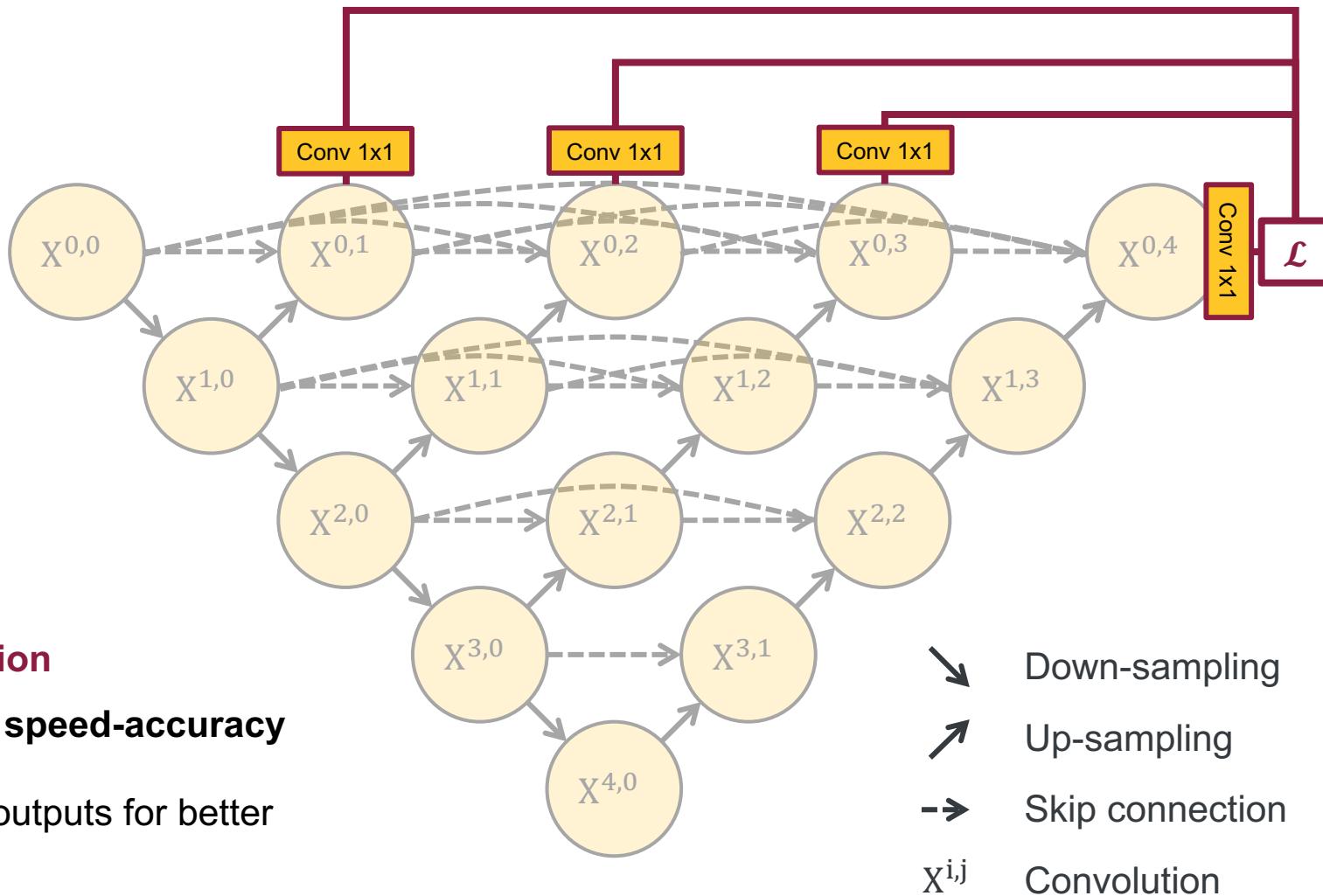






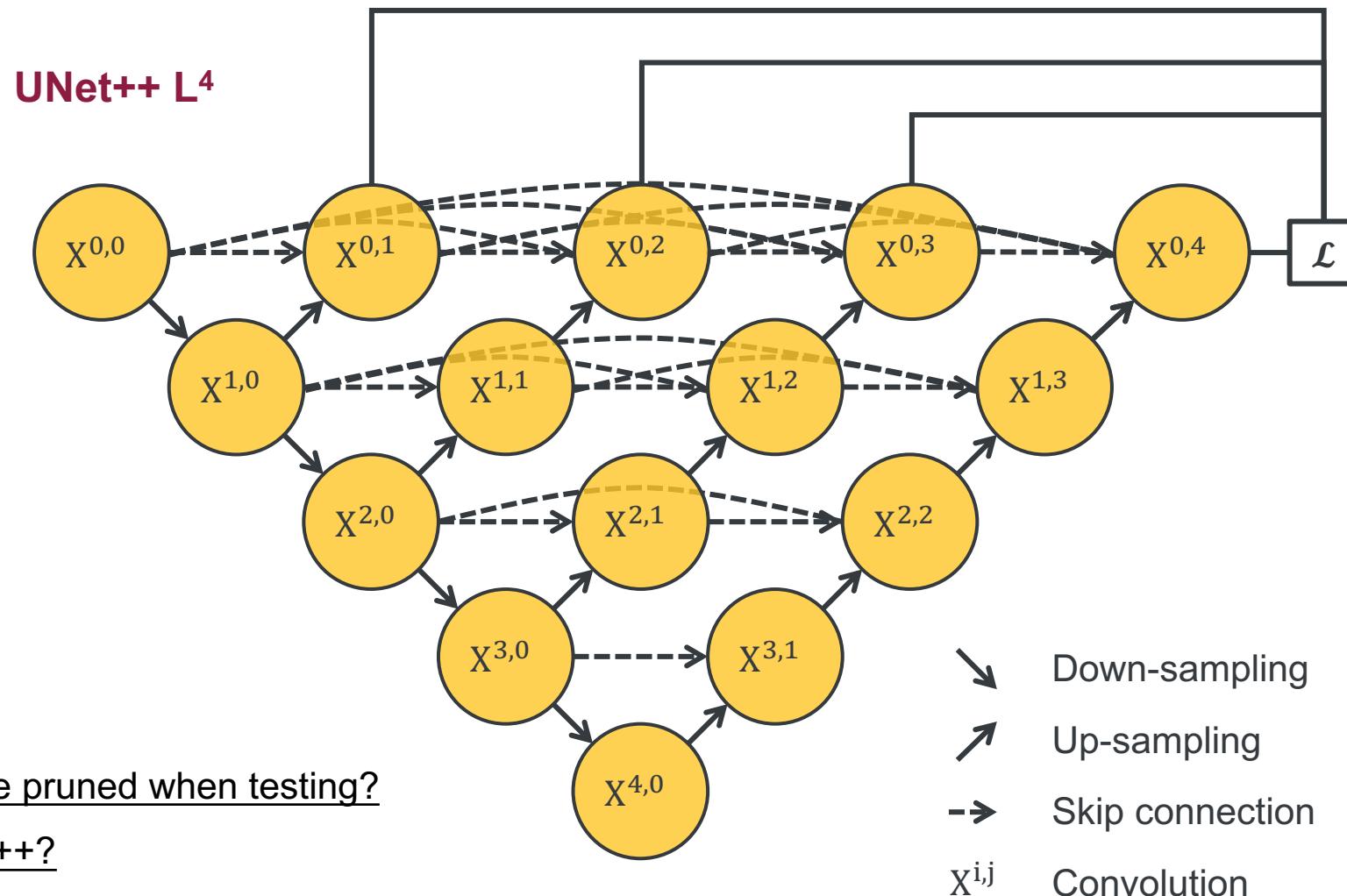




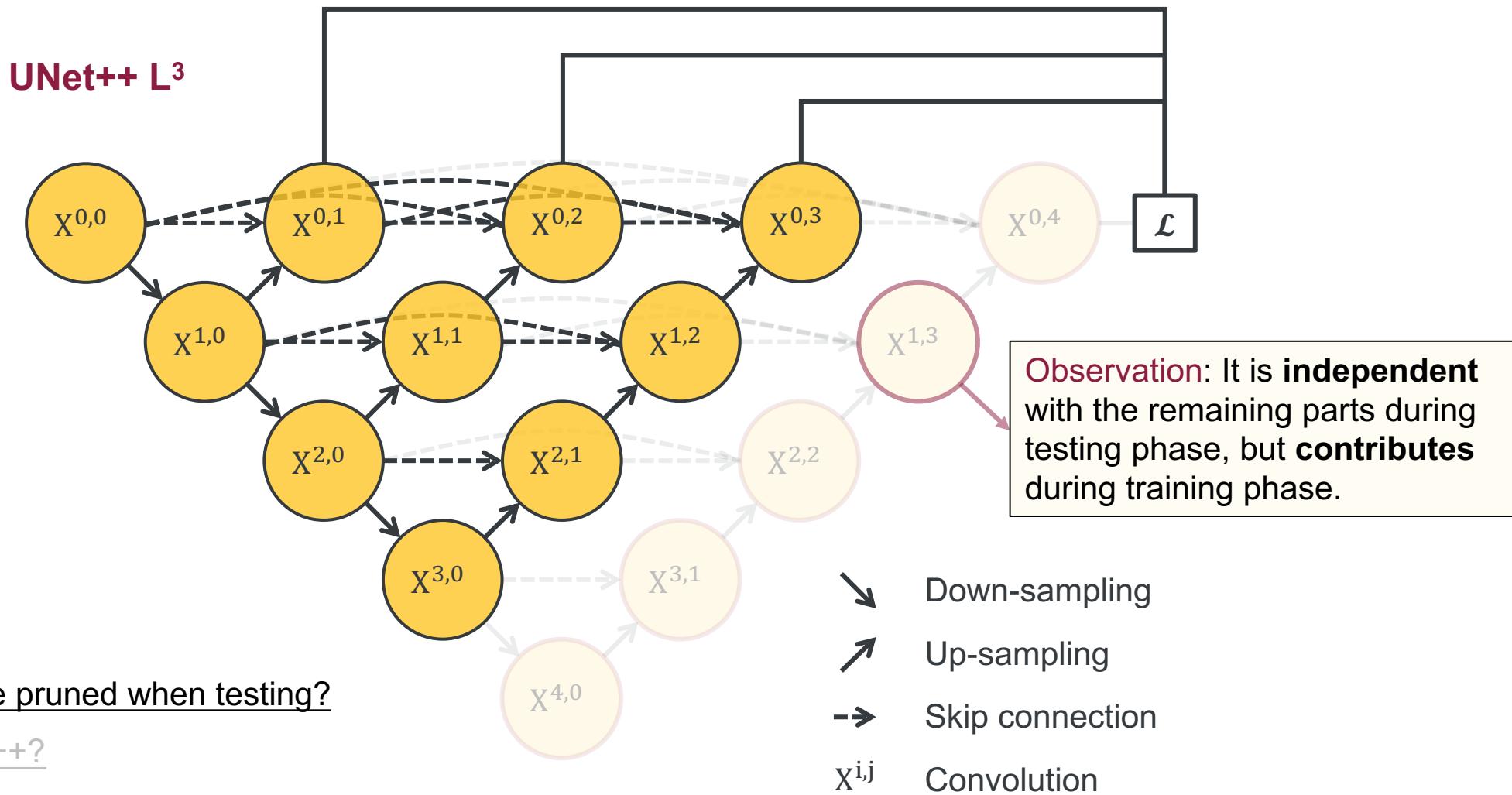


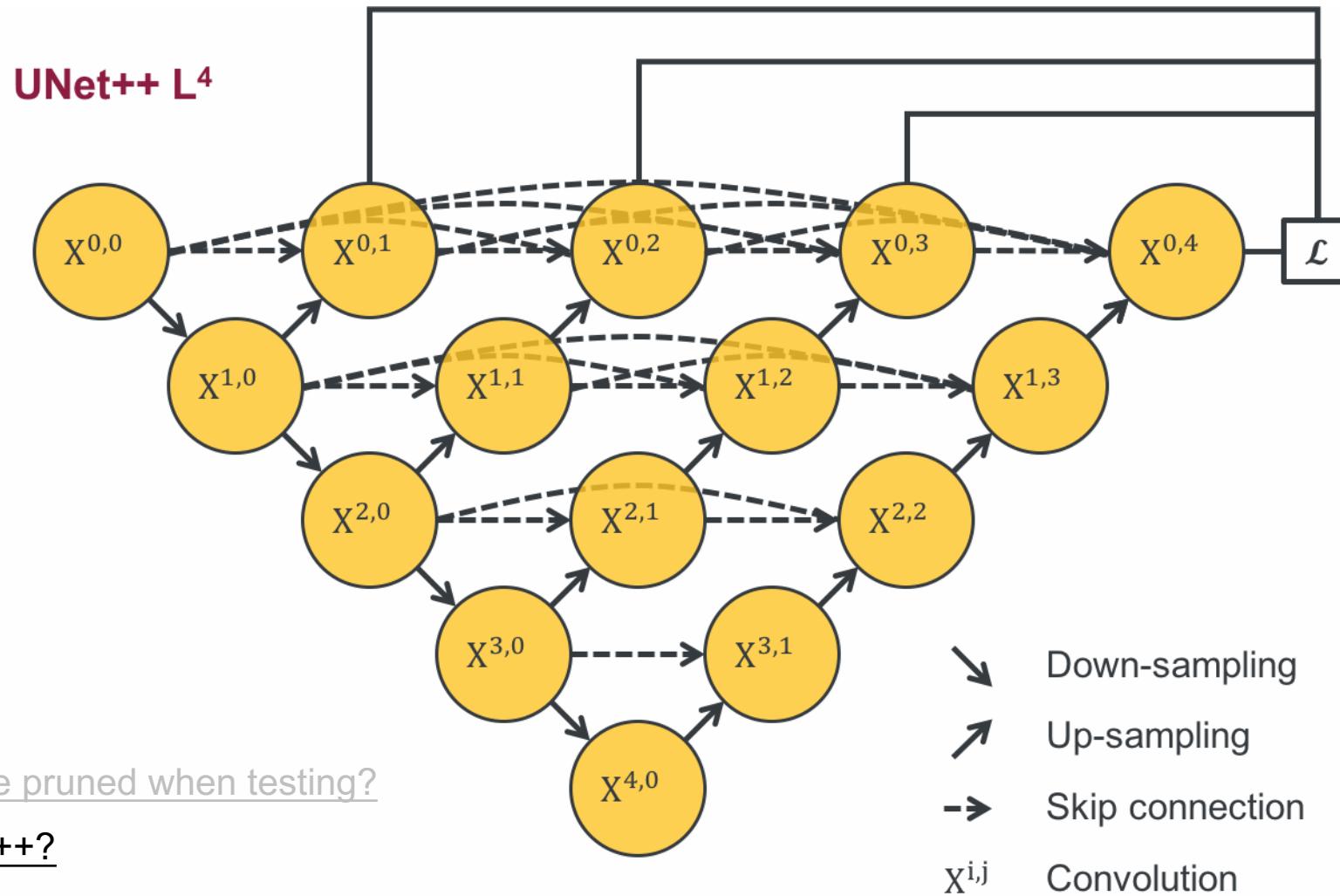
The use of deep supervision

- Allow model pruning via **speed-accuracy** trade-off.
- Ensemble **multi-depth** outputs for better accuracy.

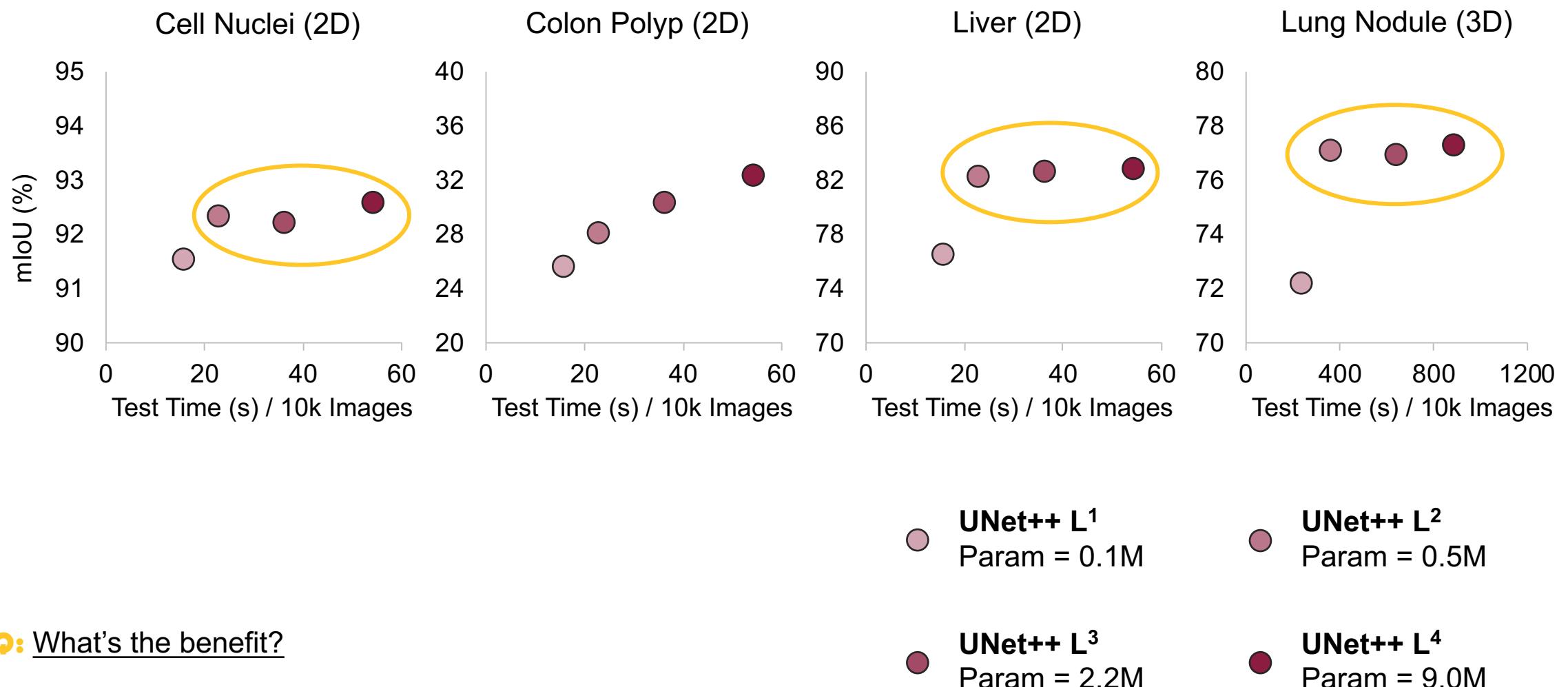


- Q: Why UNet++ can be pruned when testing?
- Q: How to prune UNet++?
- Q: What's the benefit?

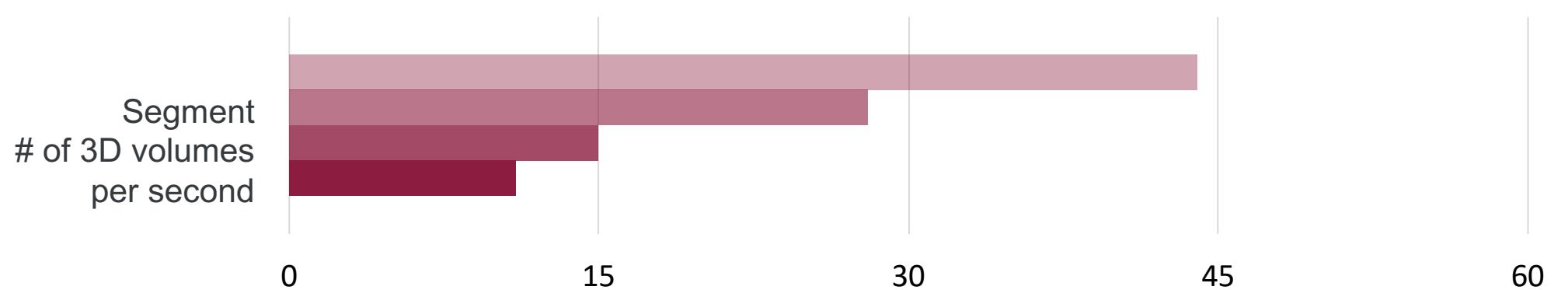
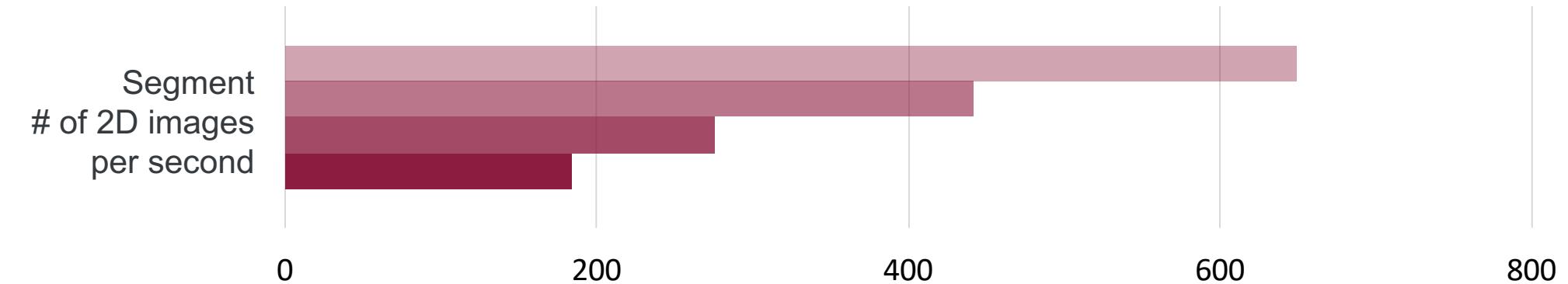




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Q: What's the benefit?

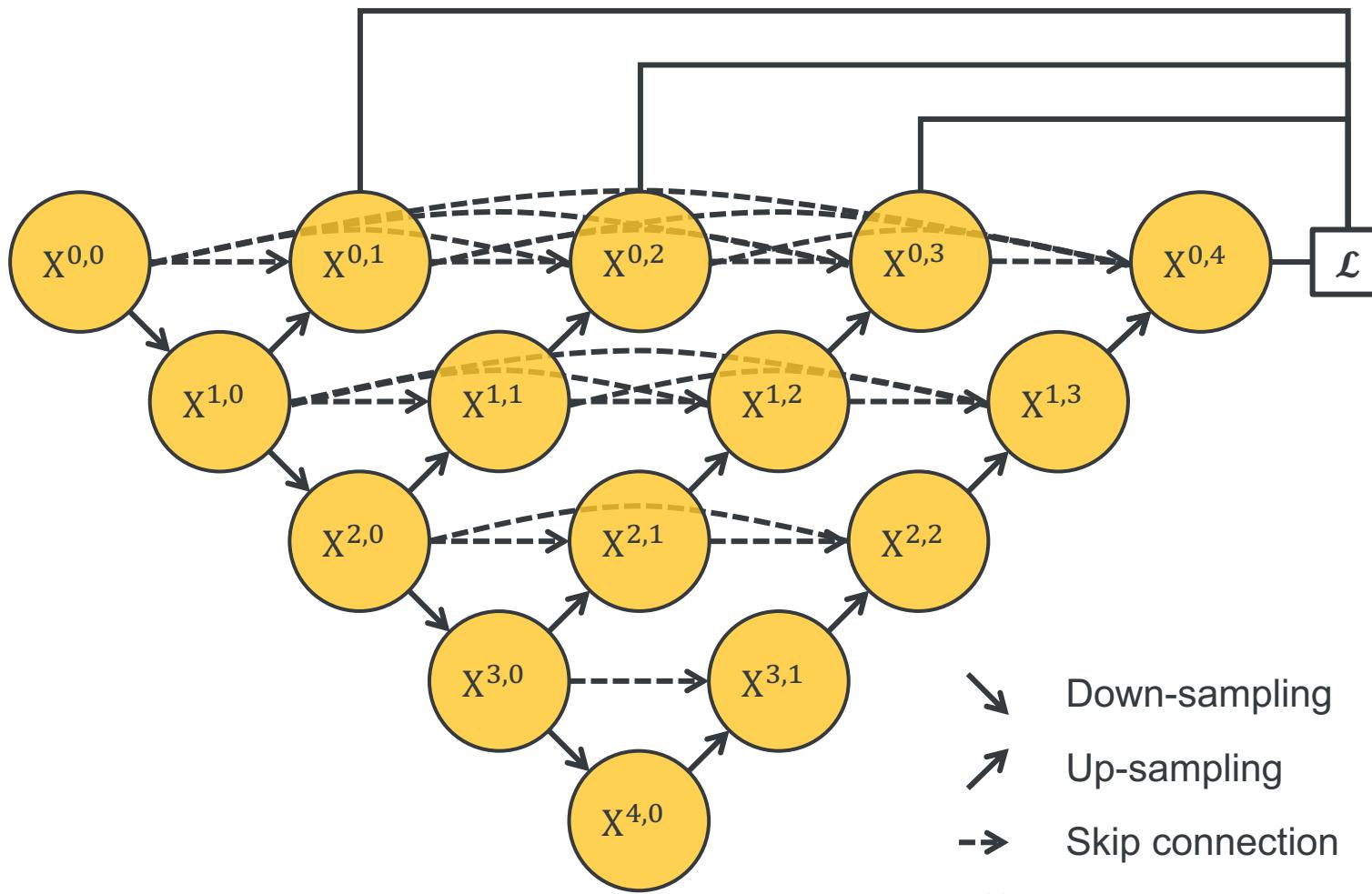


In one second, it segments

- **260 2D images more,**
- **16 3D volumes more.**

Q: What's the benefit?

- **UNet++ L¹**
Param = 0.1M
- **UNet++ L²**
Param = 0.5M
- **UNet++ L³**
Param = 2.2M
- **UNet++ L⁴**
Param = 9.0M



❑ Paper

<https://arxiv.org/abs/1807.10165>

❑ Code

<https://github.com/MrGiovanni/Nested-UNet>

❑ Weibo

@MrGiovanni

UNet++: A Nested U-Net Architecture for Medical Image Segmentation

Zongwei Zhou, Md Mahfuzur Rahman Siddiquee, Nima Tajbakhsh, and Jianming Liang

Arizona State University

Paper

<https://arxiv.org/abs/1807.10165>

Code

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Weibo

[@MrGiovanni](#)